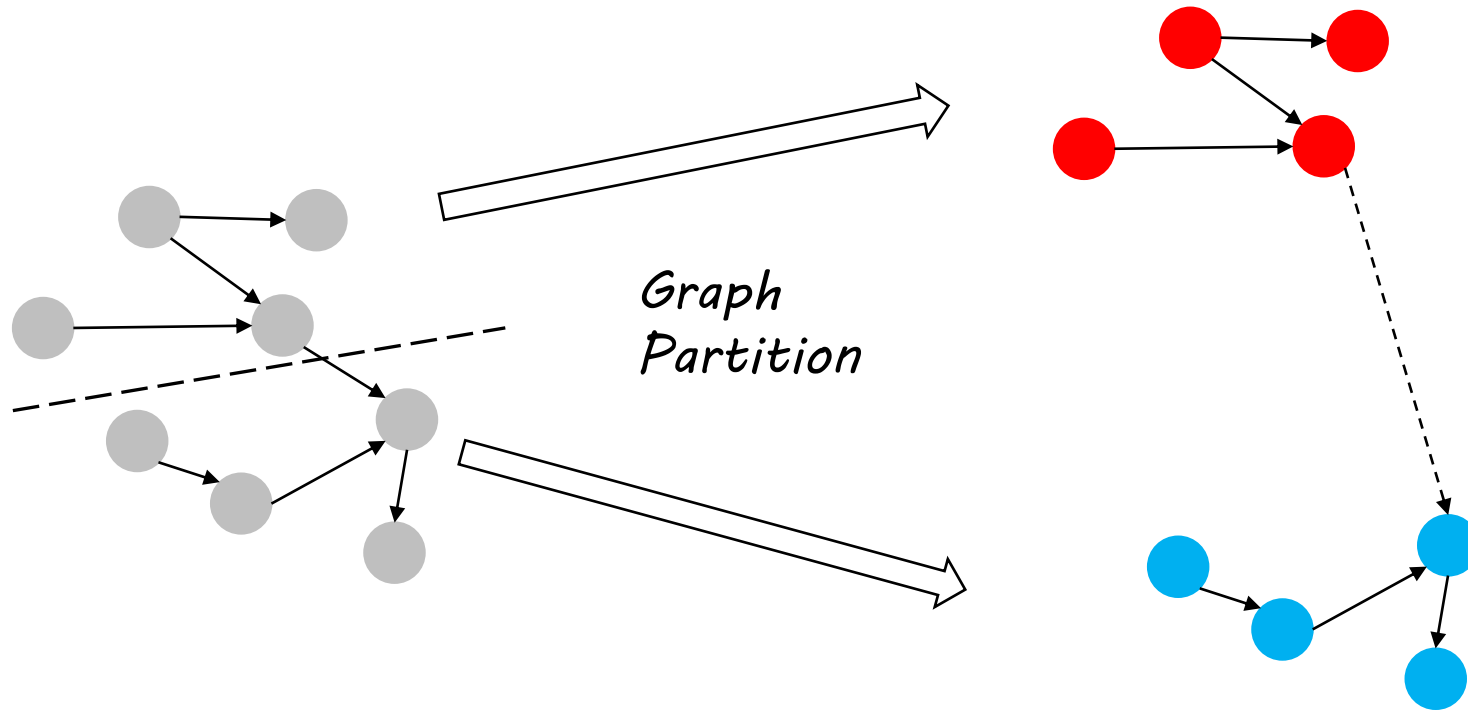


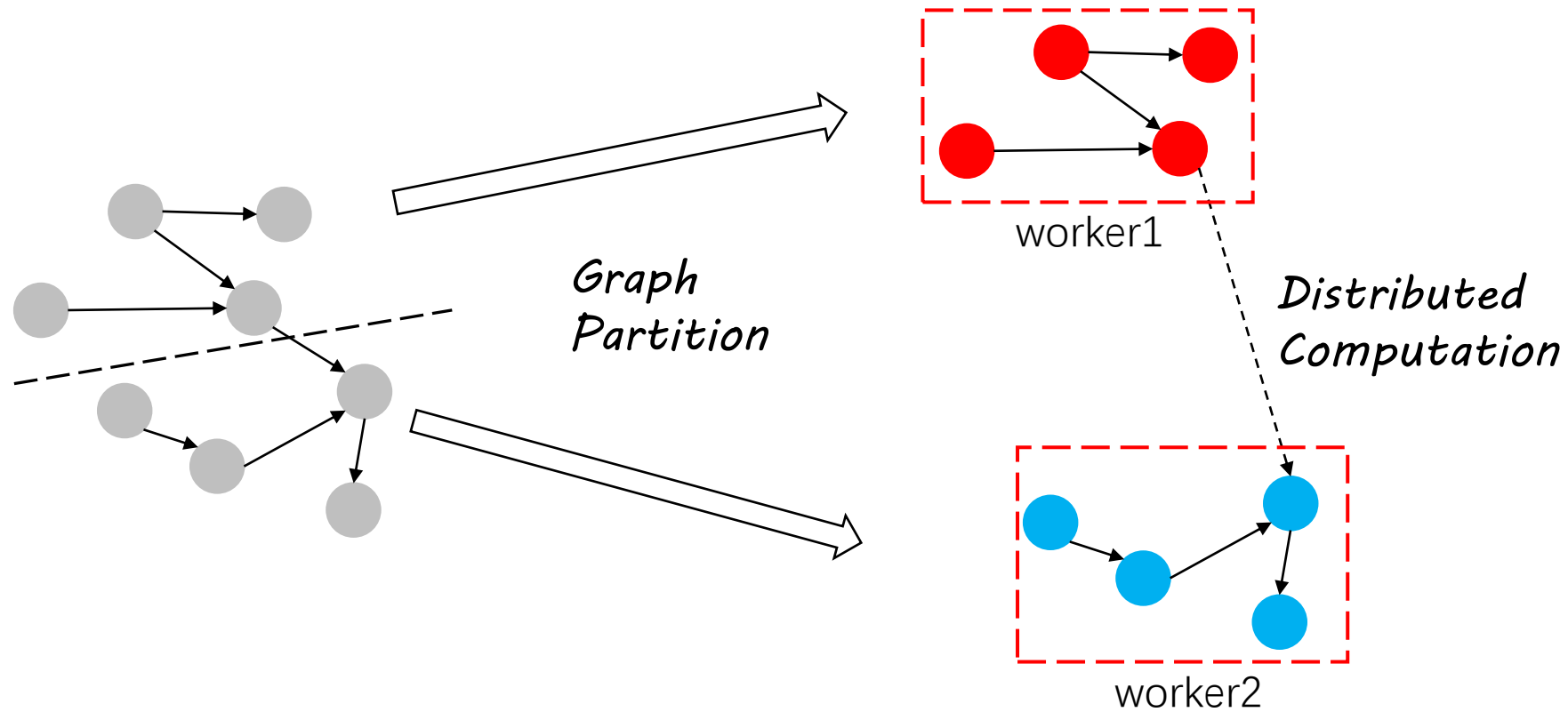
HBP: *Hotness Balanced Partition* for Prioritized Iterative Graph Computations

Shufeng Gong, Yanfeng Zhang, and Ge Yu
Northeastern University, China

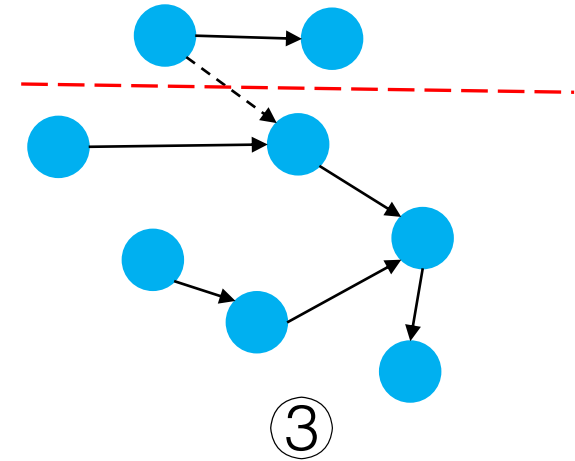
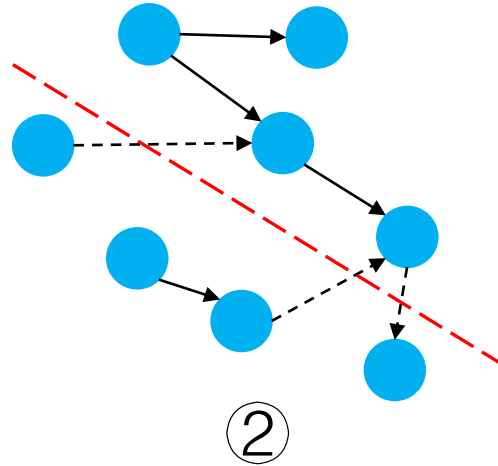
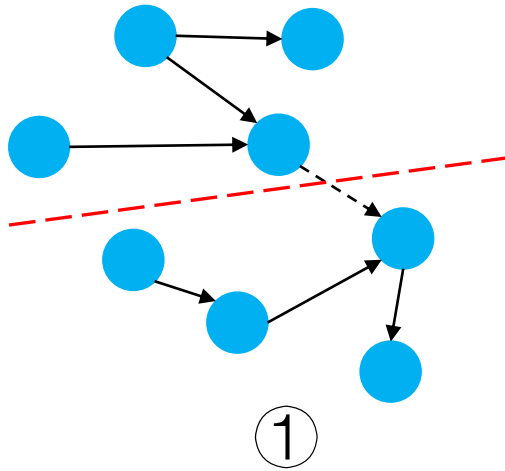
Distributed Graph Computation



Distributed Graph Computation

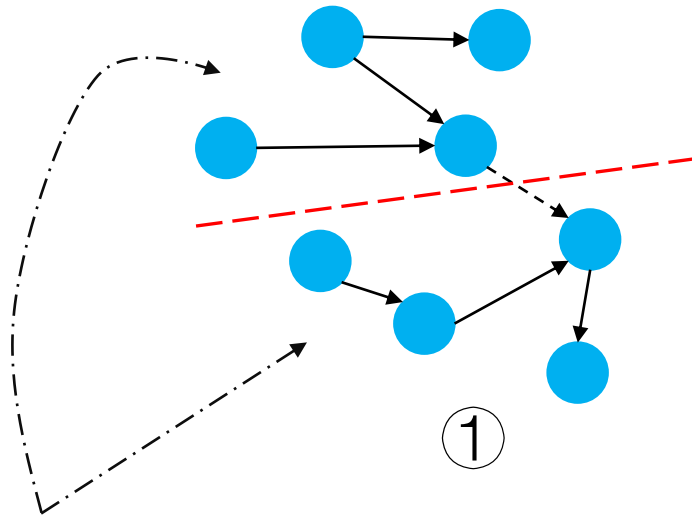


Graph Partition

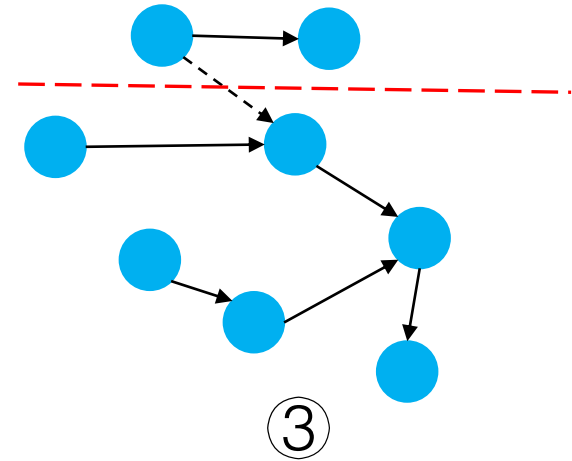
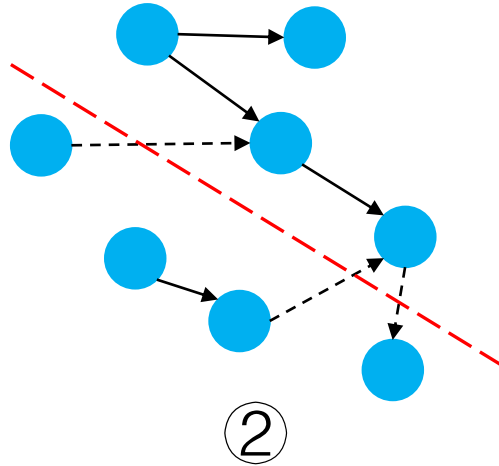


Different graph partition schemes may result in different graph processing performance.

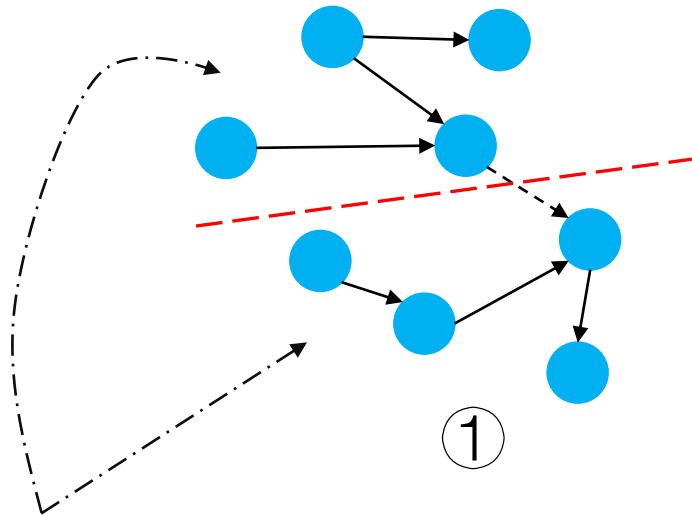
Graph Partition



*each partition has the
same number of vertices
(four vertices)*



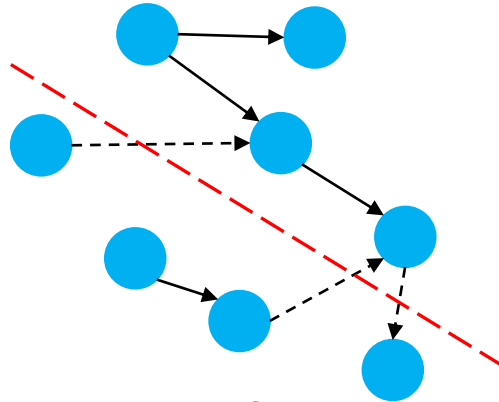
Graph Partition



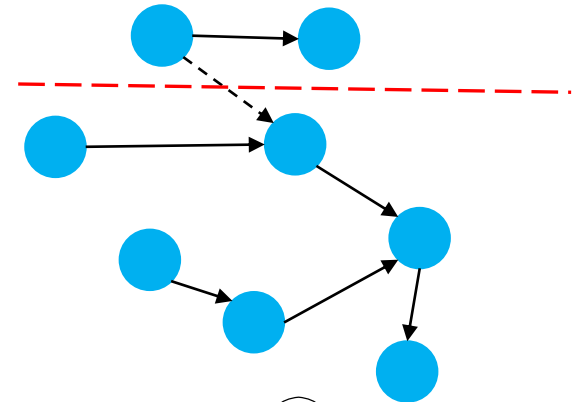
①

*each partition has the
same number of vertices
(four vertices)*

Workload Balance

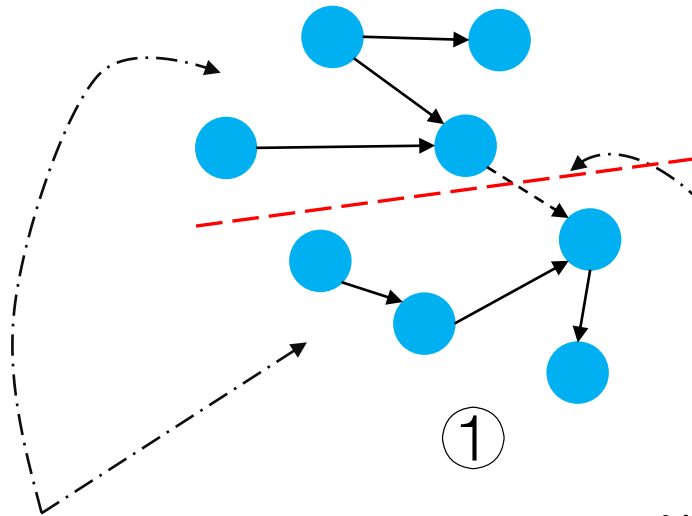


②



③

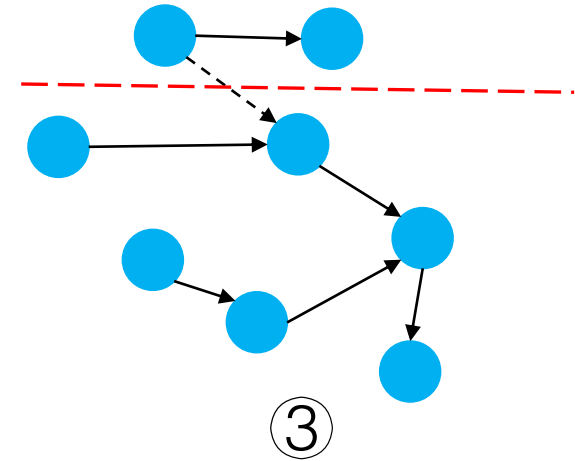
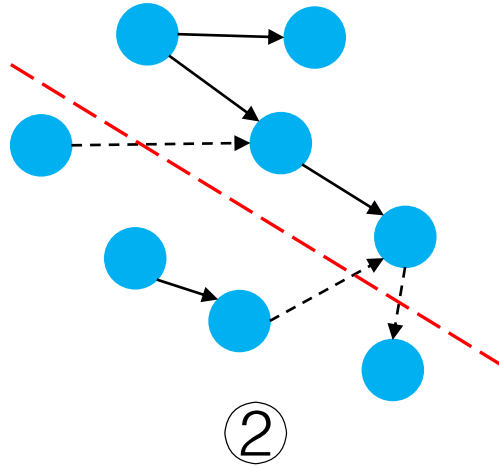
Graph Partition



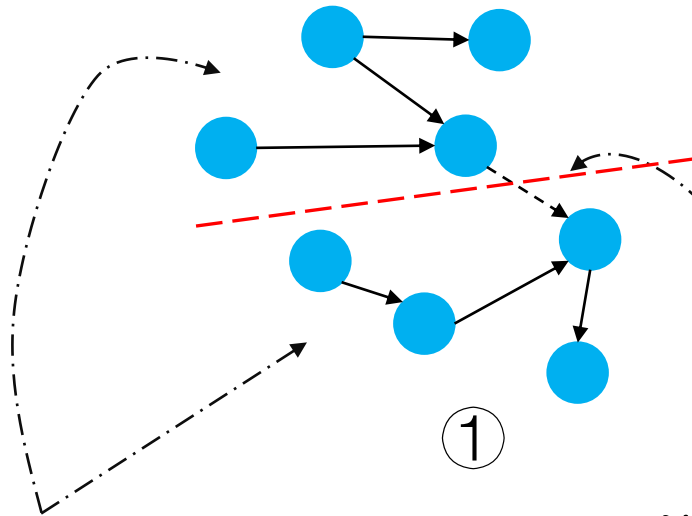
*each partition has the
same number of vertices
(four vertices)*

Workload Balance

*one pair of vertices
communicate between
different partitions*



Graph Partition

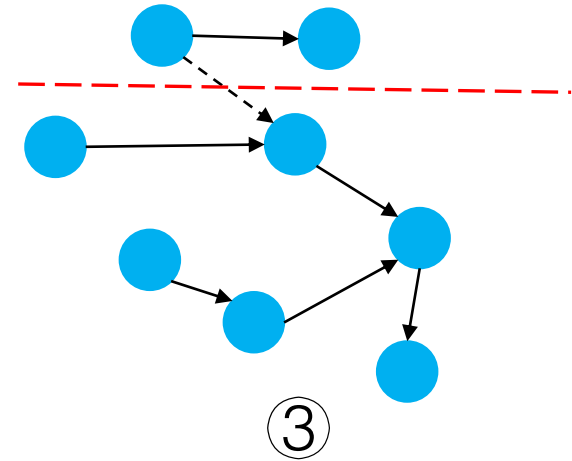
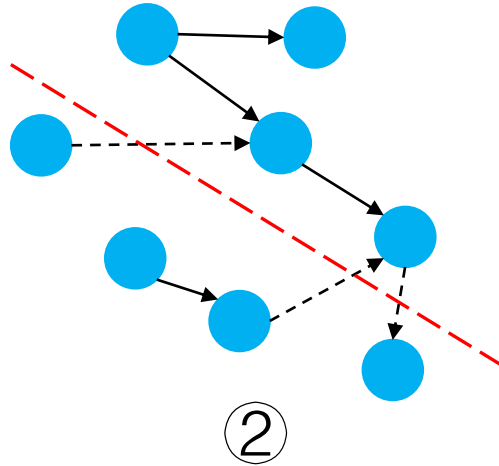


*each partition has the
same number of vertices
(four vertices)*

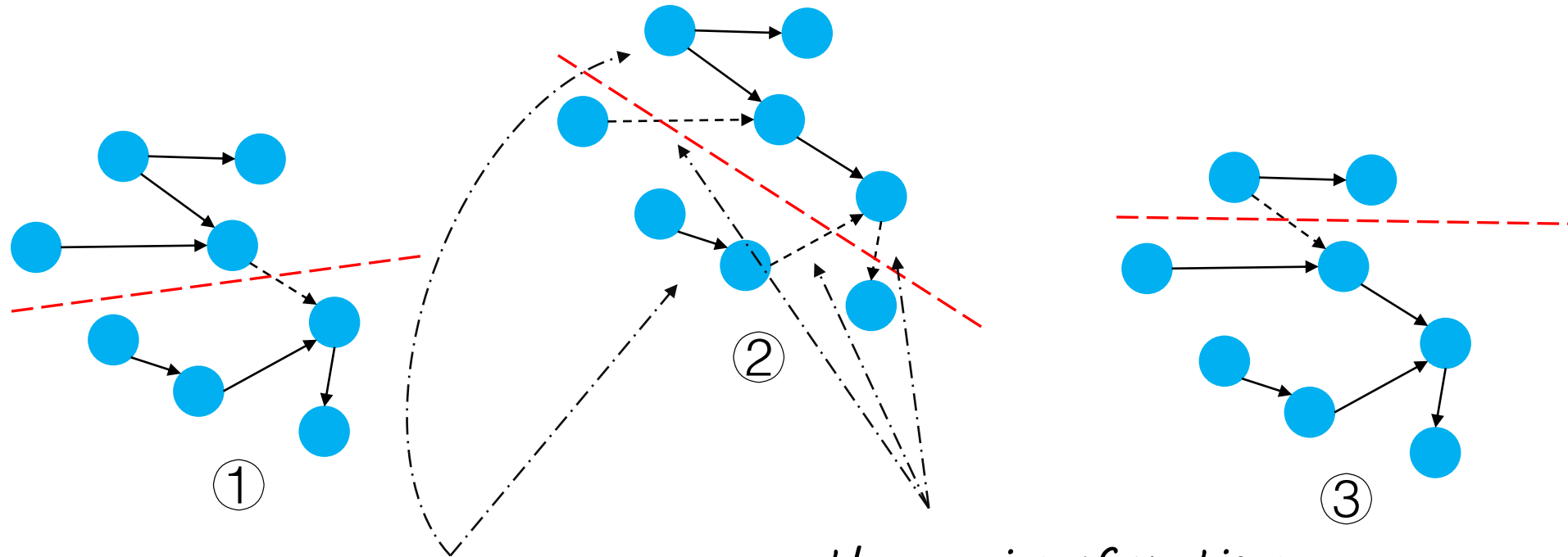
Workload Balance

*one pair of vertices
communicate between
different partitions*

Less Communication



Graph Partition



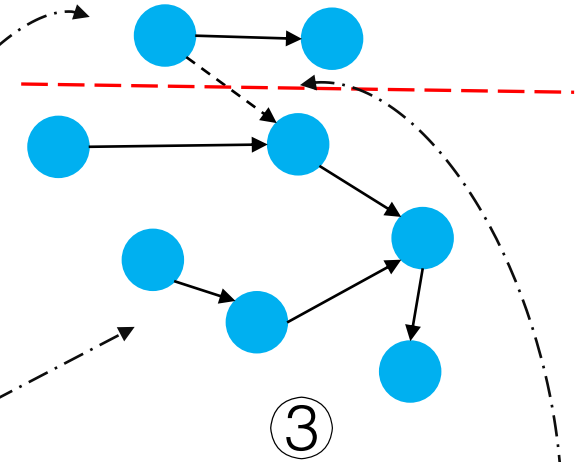
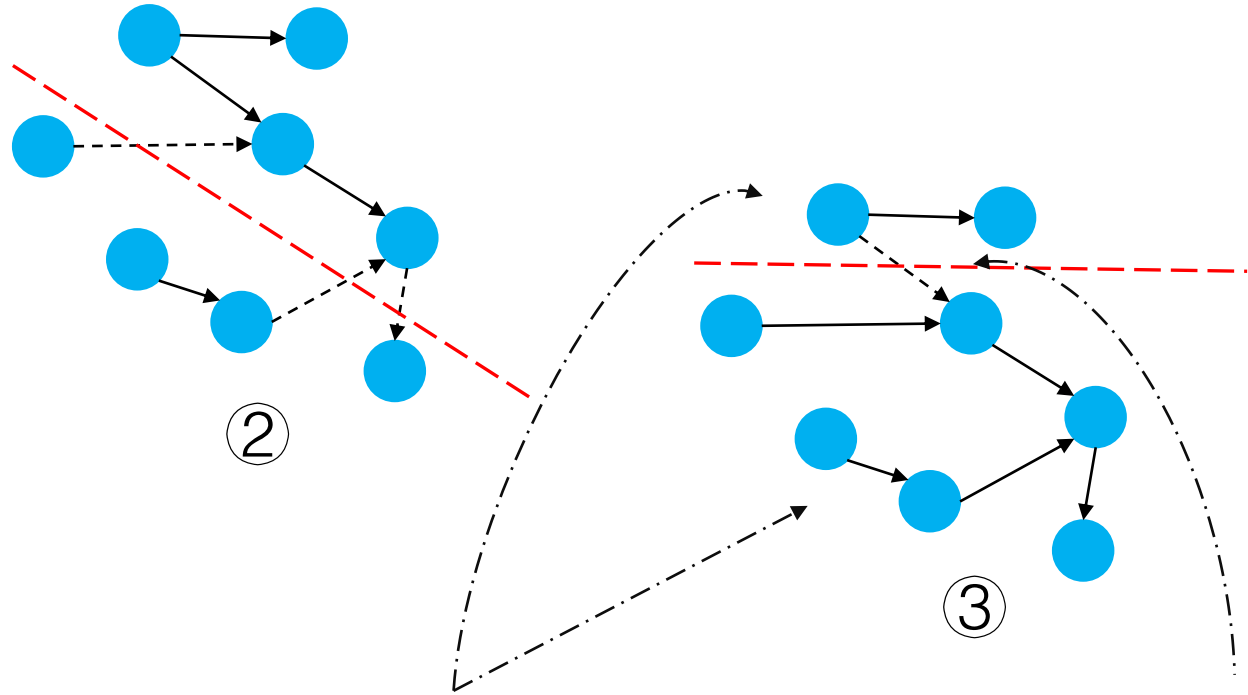
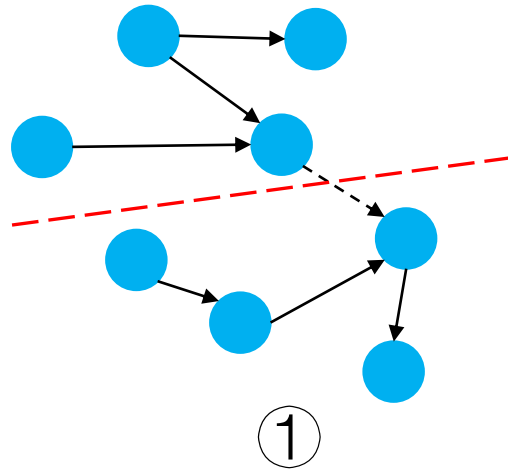
*each partition has the
same number of vertices
(four vertices)*

Workload Balance

*three pairs of vertices
communicate between
different partitions*

More Communication

Graph Partition



each partition has a different
number of vertices (*two*
vertices vs. *six vertices*)

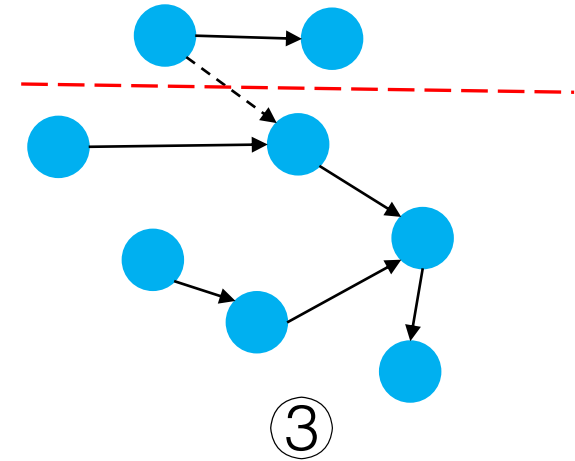
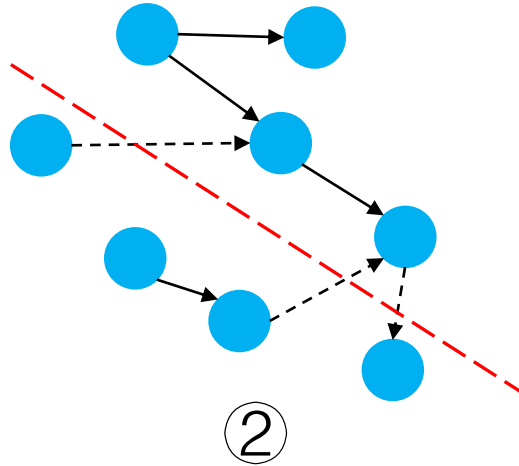
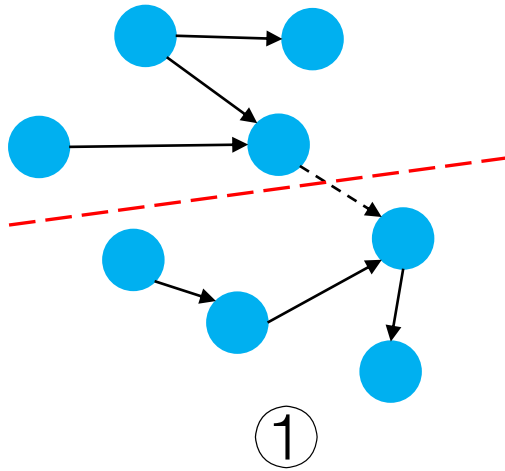
Workload Imbalance



wait time

one pair of vertices
communicate between
different partitions
Less Communication

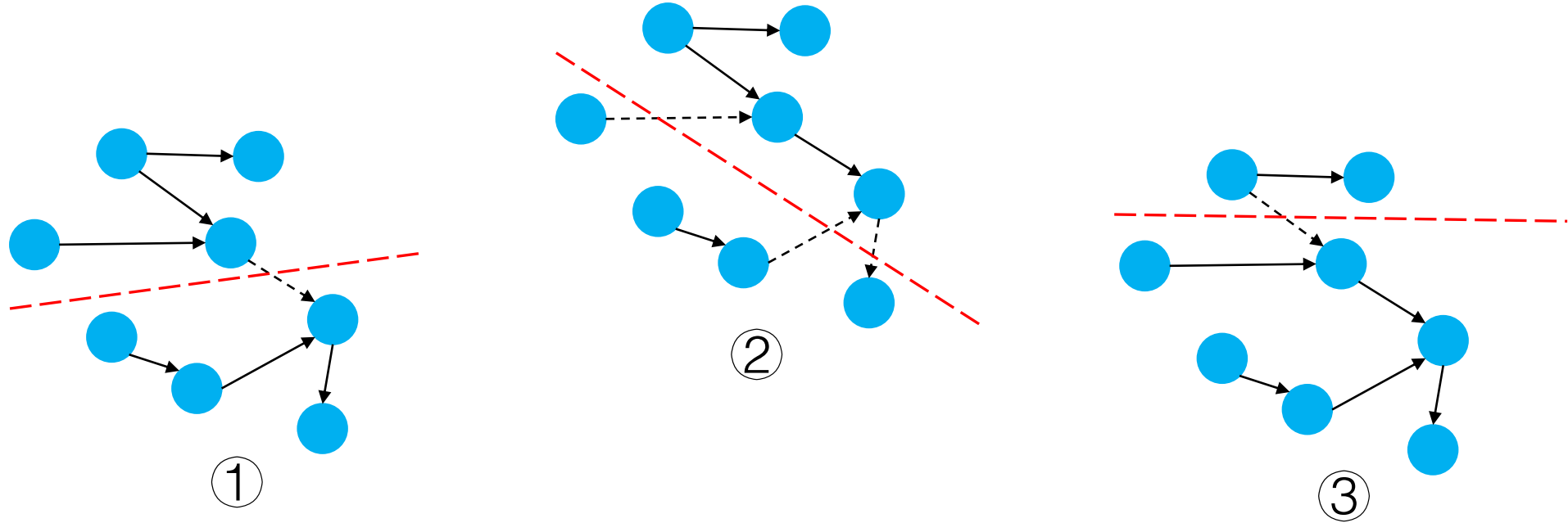
Graph Partition



A good partition can

- 1. Reduce wait time*
- 2. Minimize communication cost*

Graph Partition



- Goals:**
- 1. Balance the number of vertices
 - 2. Minimize the number of edge cuts

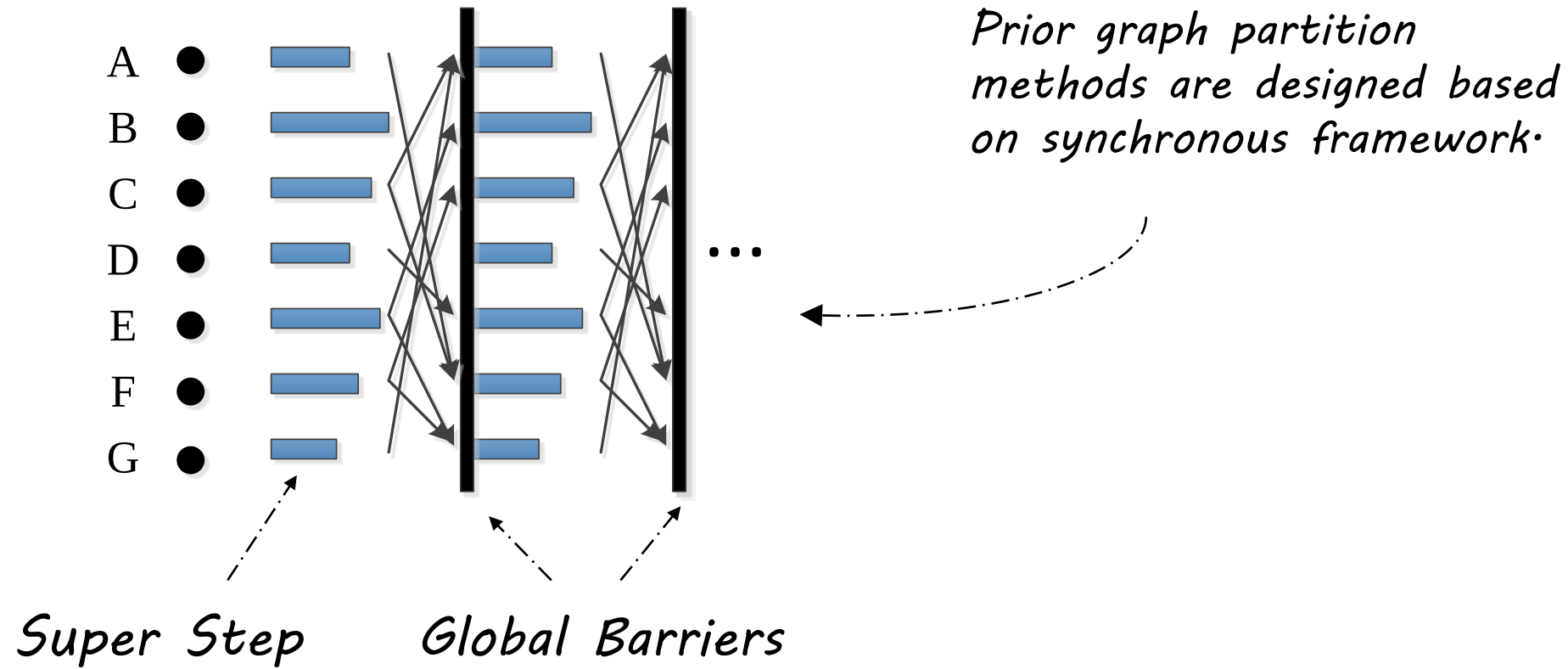
Related Works

Metis¹, Leopard², Fennel³, HDRF⁴, Spinner⁵, Sheep⁶, NE⁷

They assume the workload depends on vertices (vertex centric) or edges (edge centric), and the communication cost depends on the number of edge cuts or vertex replications.

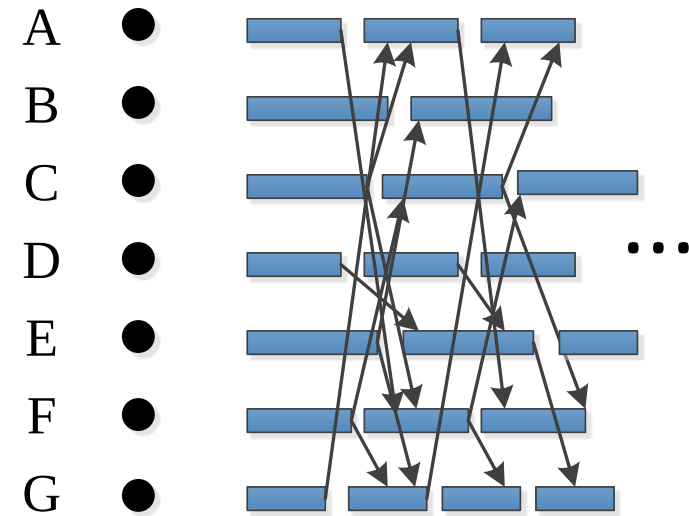
1. Karypis, George, and Vipin Kumar. "A fast and high quality multilevel scheme for partitioning irregular graphs." *SISC* 20.1 (1998): 359-392.
2. Huang, Jiewen, and Daniel J. Abadi. "Leopard: Lightweight edge-oriented partitioning and replication for dynamic graphs." *Proceedings of the VLDB* 2016.
3. Tsourakakis, Charalampos, et al. "Fennel: Streaming graph partitioning for massive scale graphs." *WSDM* 2014.
4. Petroni, Fabio, et al. "HDRF: Stream-based partitioning for power-law graphs." *CIKM* 2015.
5. Martella, Claudio, et al. "Spinner: Scalable graph partitioning in the cloud." *ICDE* 2017.
6. Margo, Daniel, and Margo Seltzer. "A scalable distributed graph partitioner." *VLDB* 2015.
7. Zhang, Chenzi, et al. "Graph edge partitioning via neighborhood heuristic." *KDD* 2017.

Synchronous Frameworks

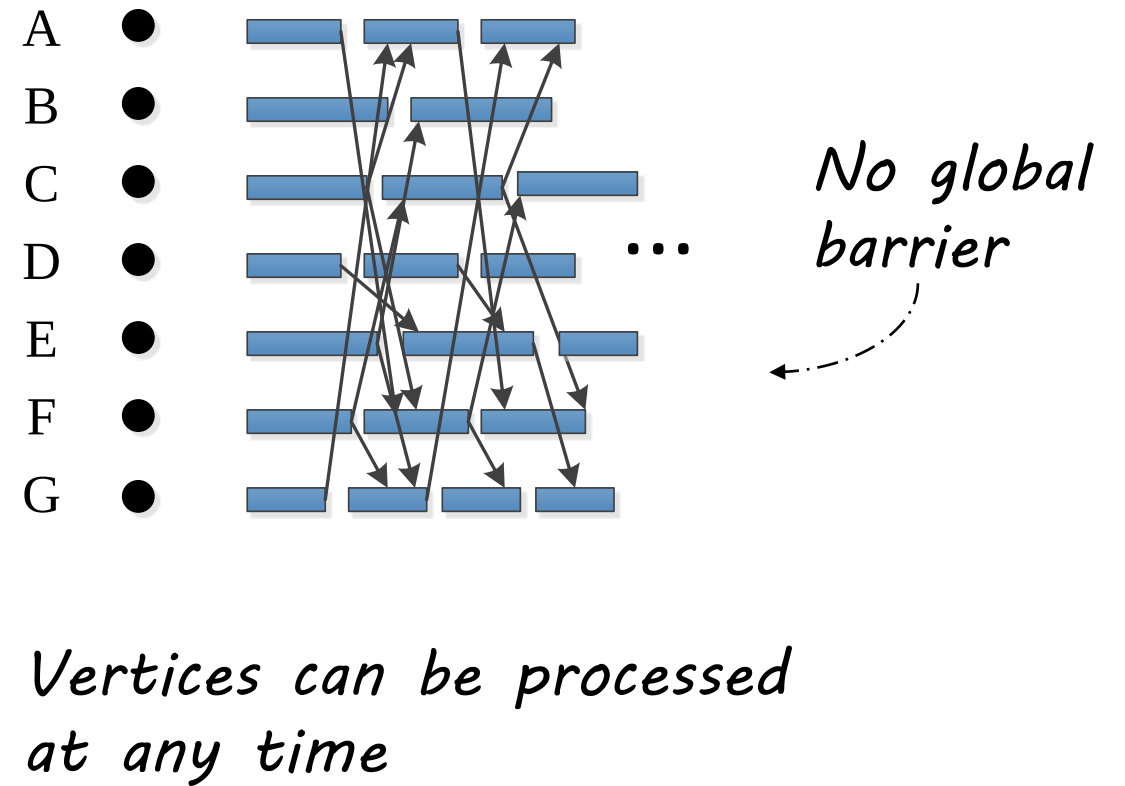
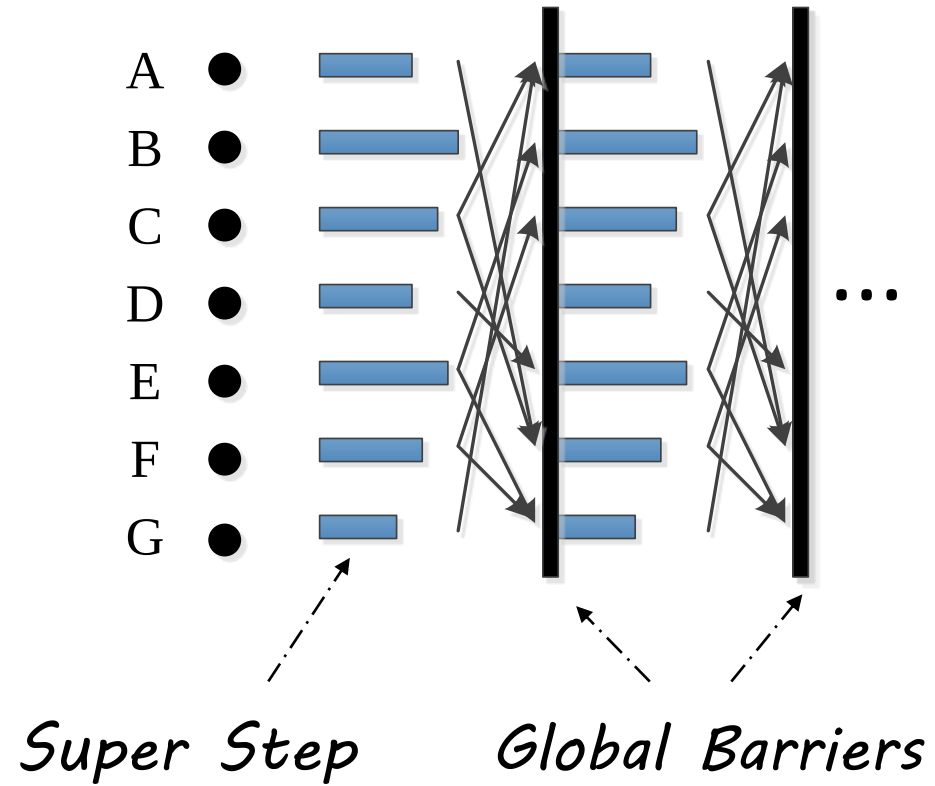


Sync & Async

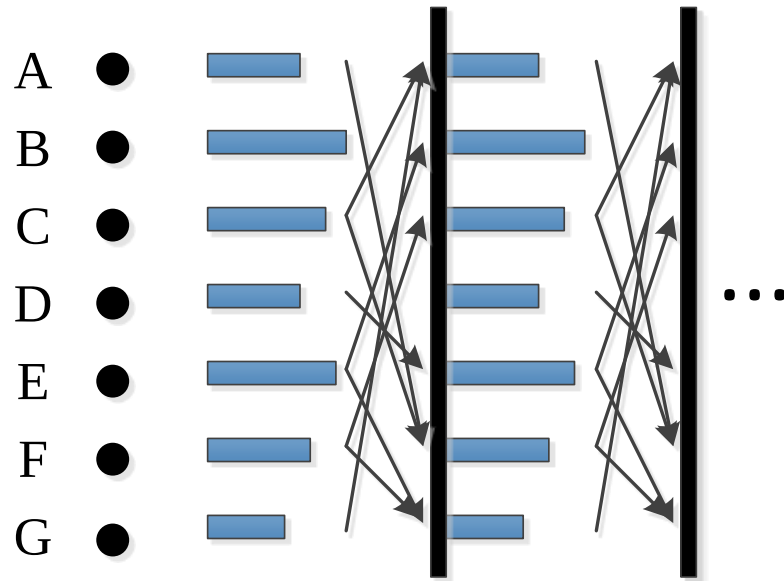
Some work pays attention to asynchronous frameworks since they can accelerate a class of iterative algorithms.



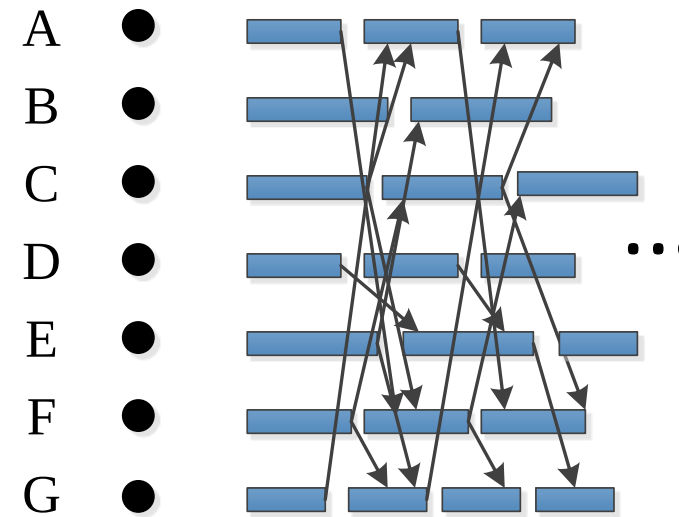
Sync & Async



Sync & Async

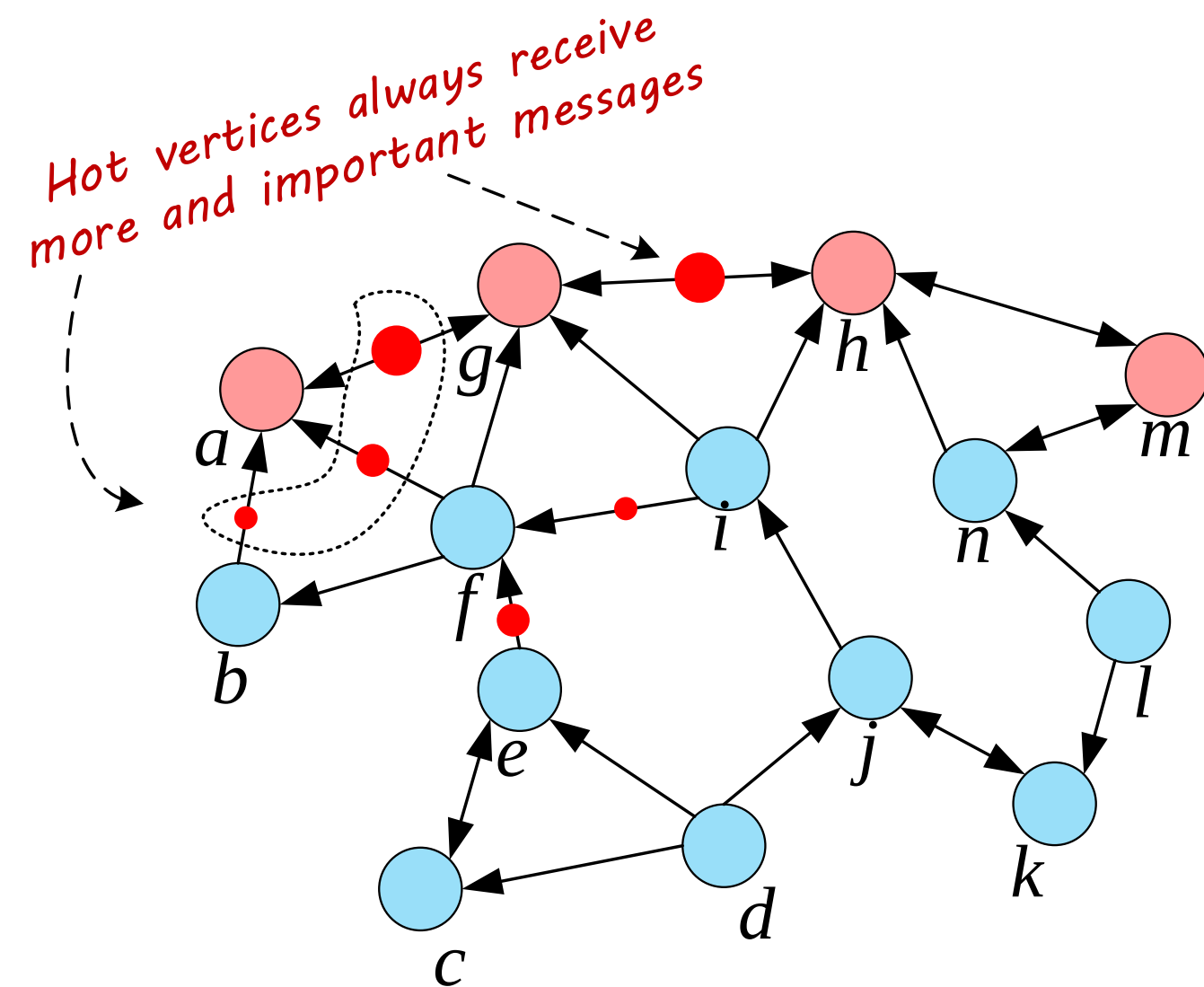


In each super step, each vertex is only processed once, and each edge only delivers one message.

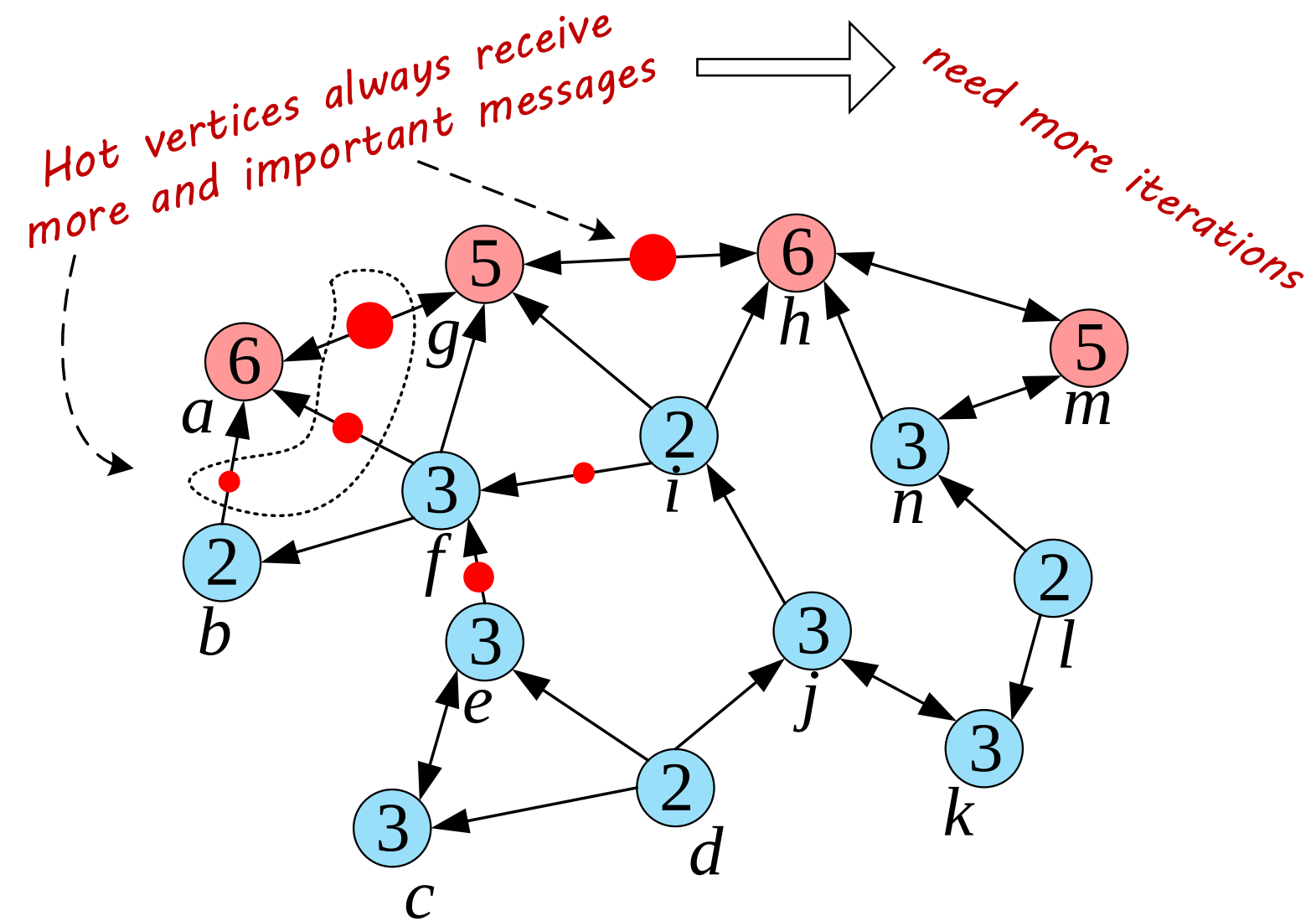


The number of updates on each vertex and the number of messages passed through each edge are not consistent.

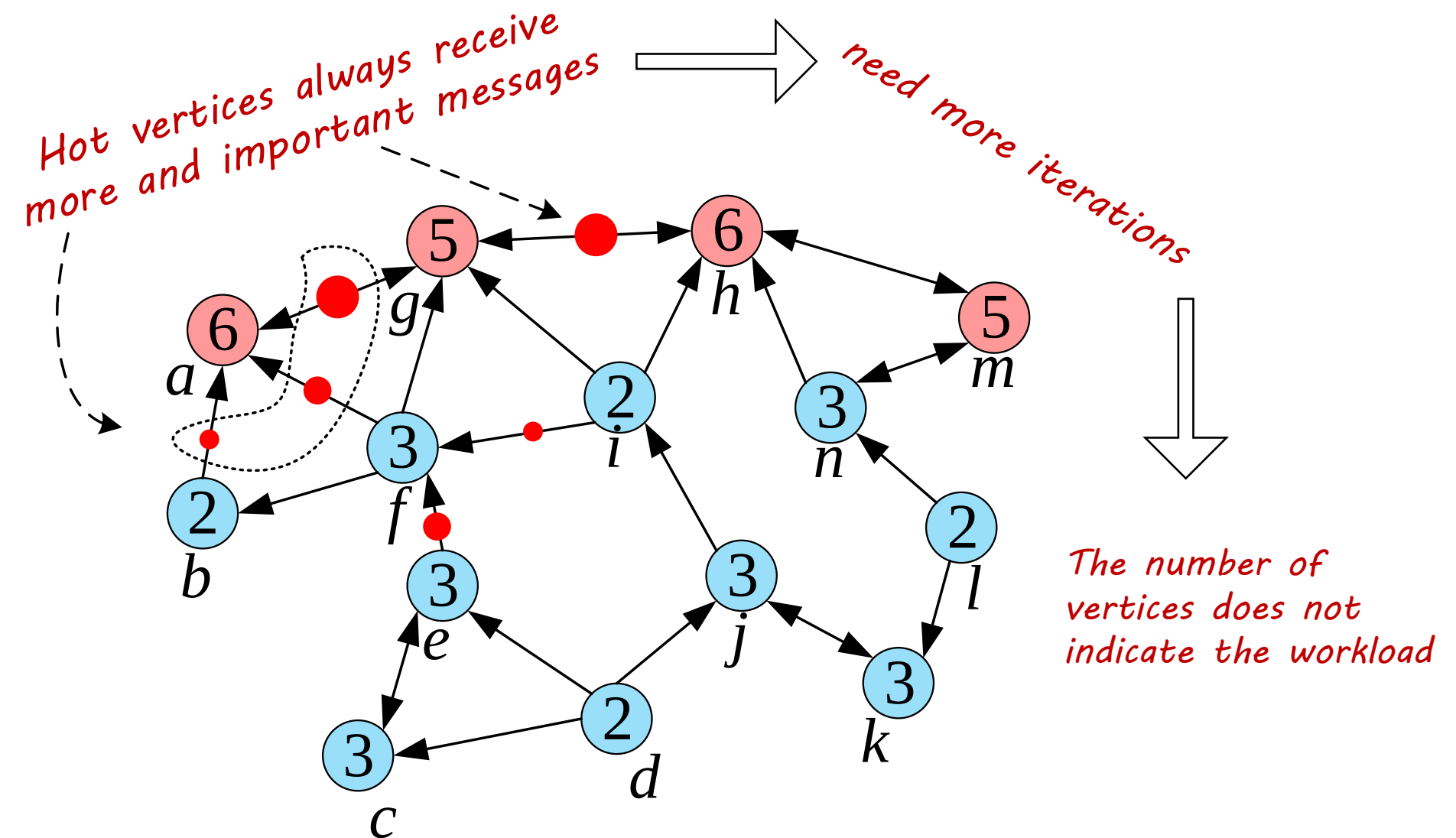
Hotness of Vertices



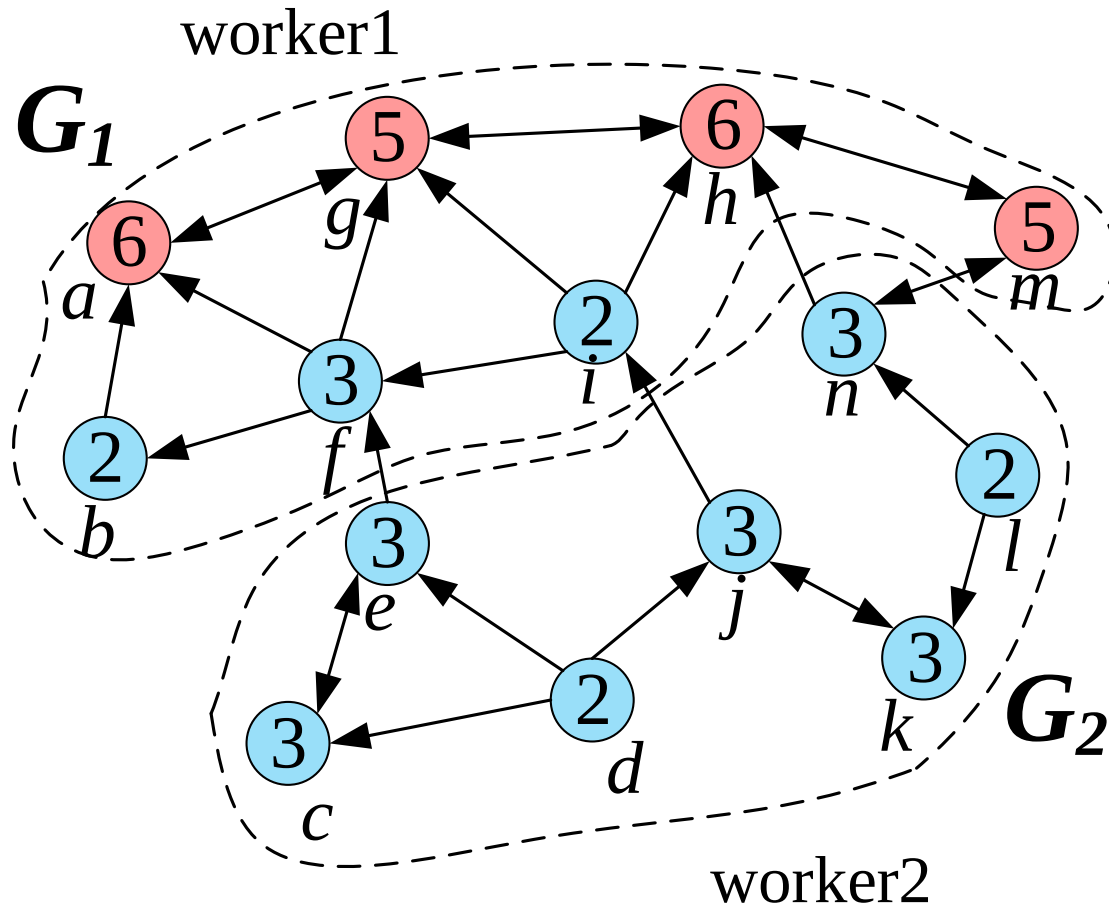
Hotness of Vertices



Hotness of Vertices



Vertex Balanced Partition

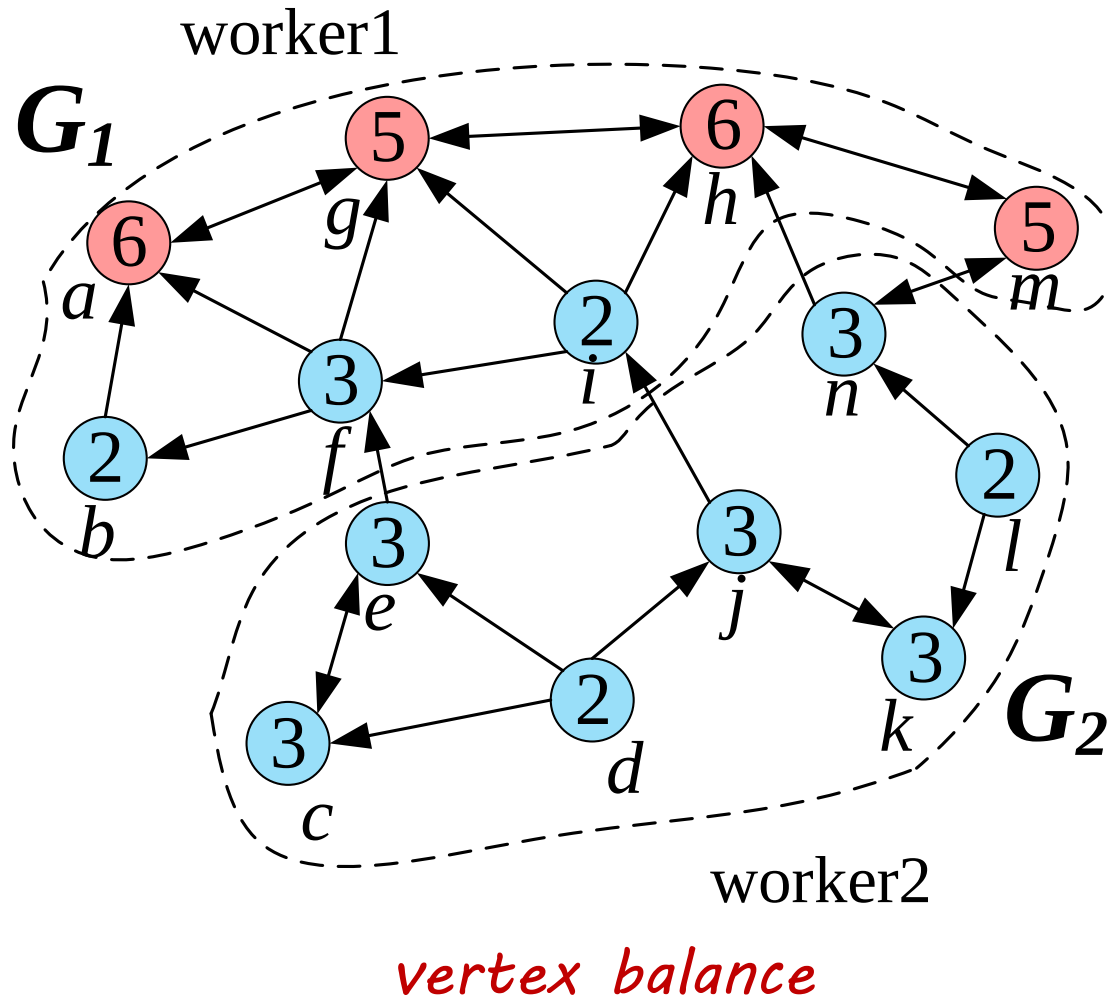


Partition graph into G_1 and G_2

*Worker1 processes G_1
Worker2 processes G_2*

vertex balance

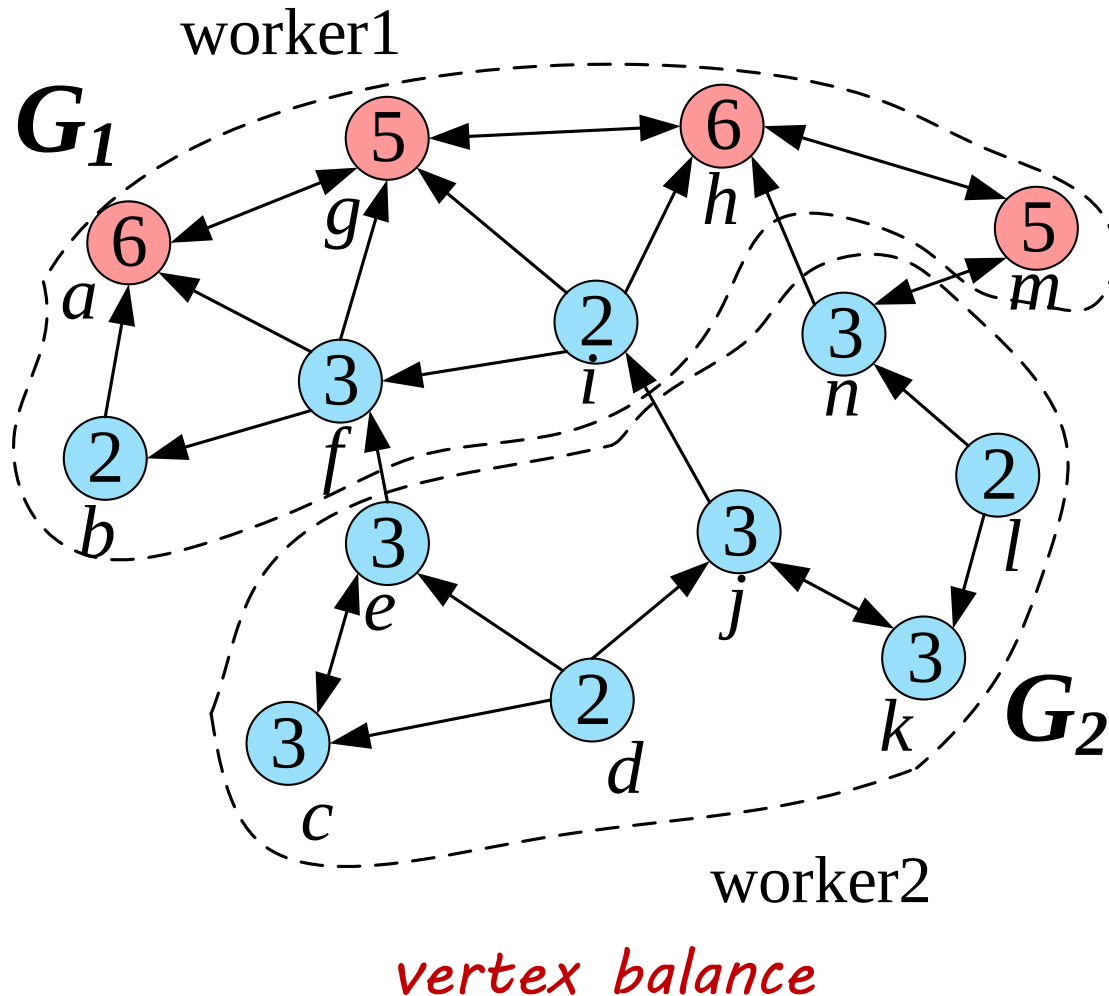
Vertex Balanced Partition



*The number of vertices in G_1 and G_2 is equal.
The sum of hotness in G_1 and G_2 is not equal.*

*Prior vertex balanced graph
partition methods do not
take the vertex hotness
into account when
partitioning graphs.*

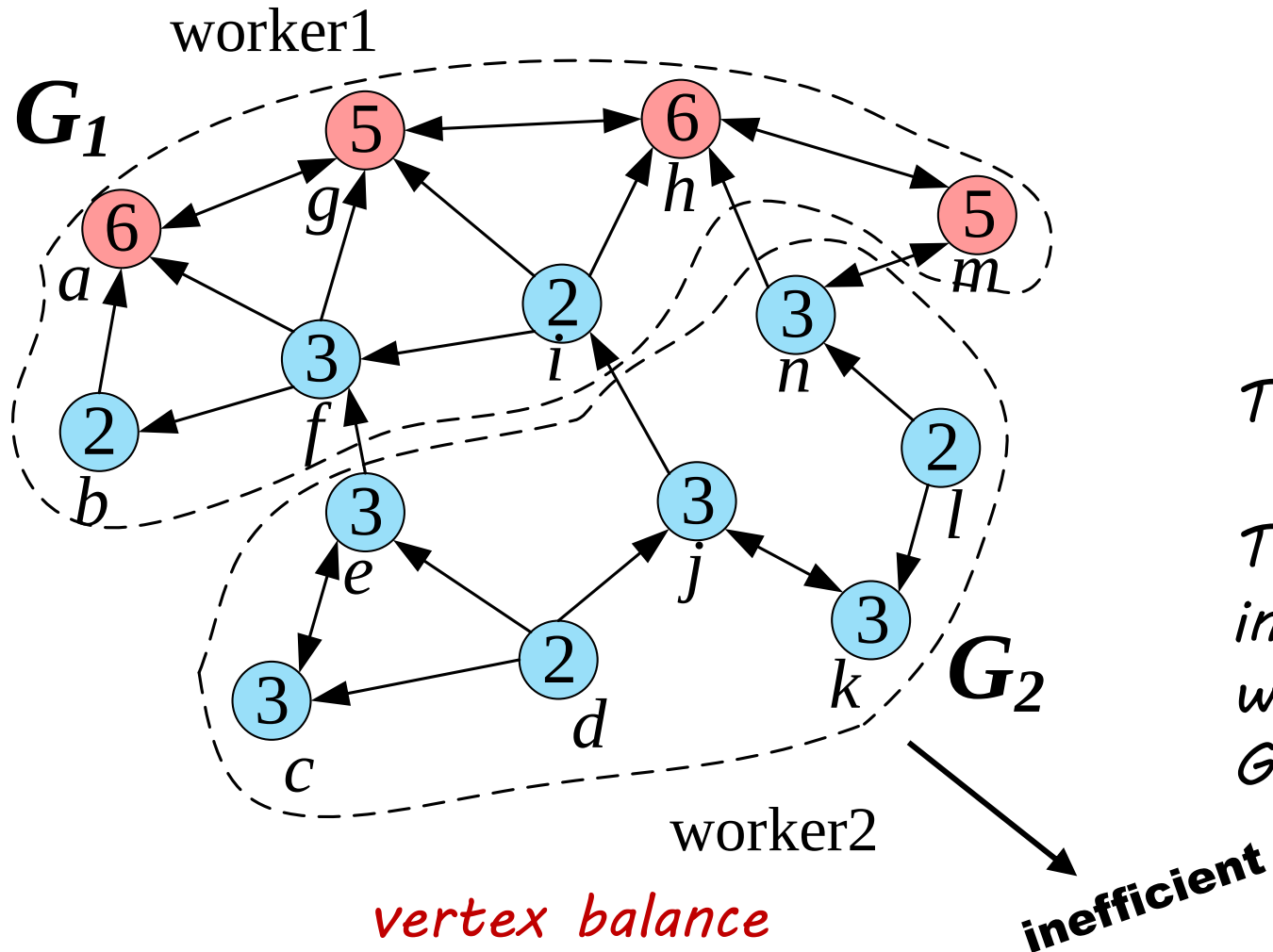
Vertex Balanced Partition



Two workers are running.

*There may be a lot of
invalid computation in
worker2 since vertices in
 G_2 need fewer iterations.*

Vertex Balanced Partition

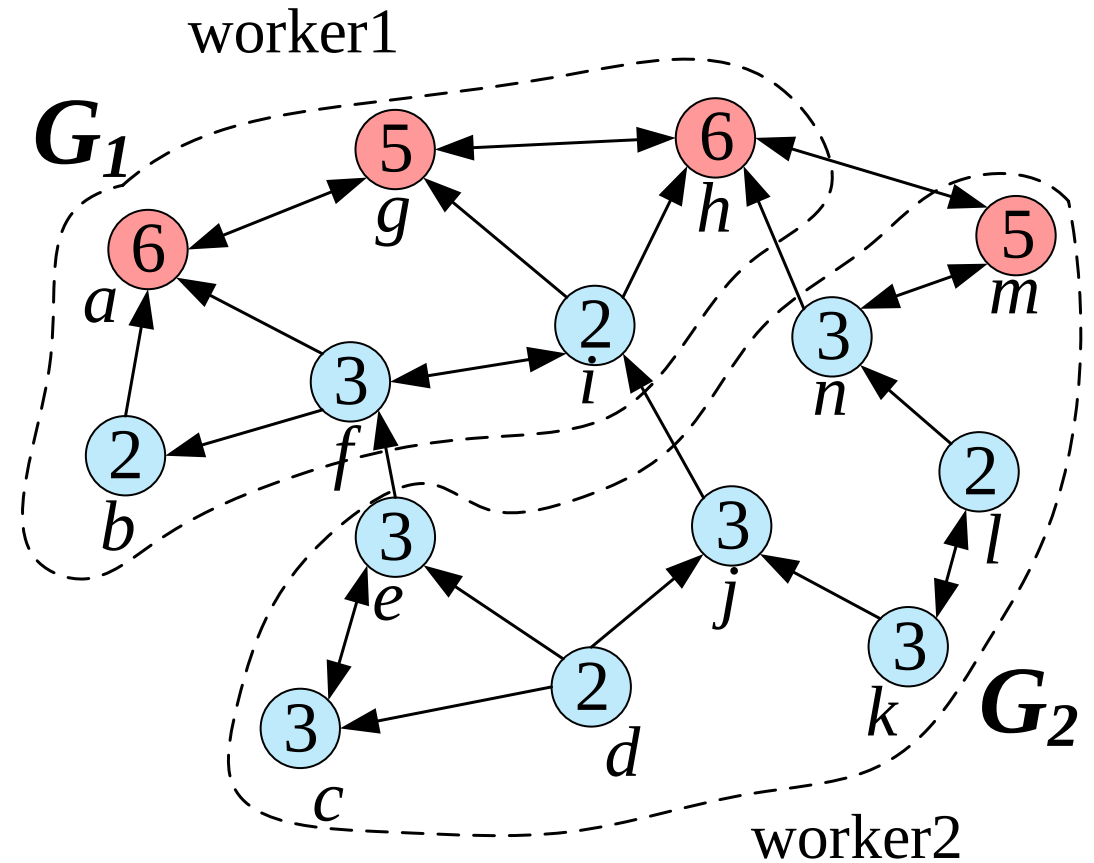


Two workers are running.

*There may be a lot of
invalid computation in
worker2 since vertices in
 G_2 need fewer iterations.*

Hotness Balanced Partition

*Sum of hotness of G_2
and G_1 is equal*



hotness balance

Hotness Balanced Partition

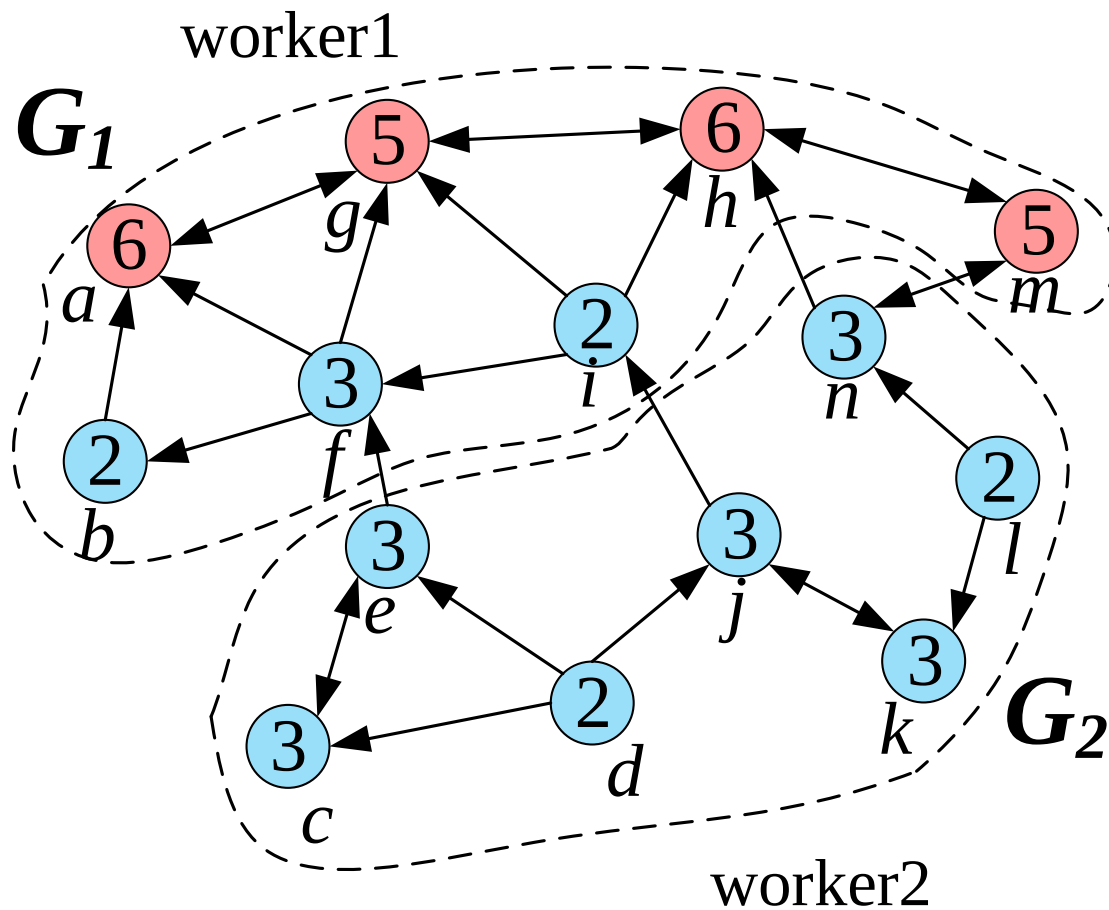


Fig. 1: vertex balance

**More valid
computation**

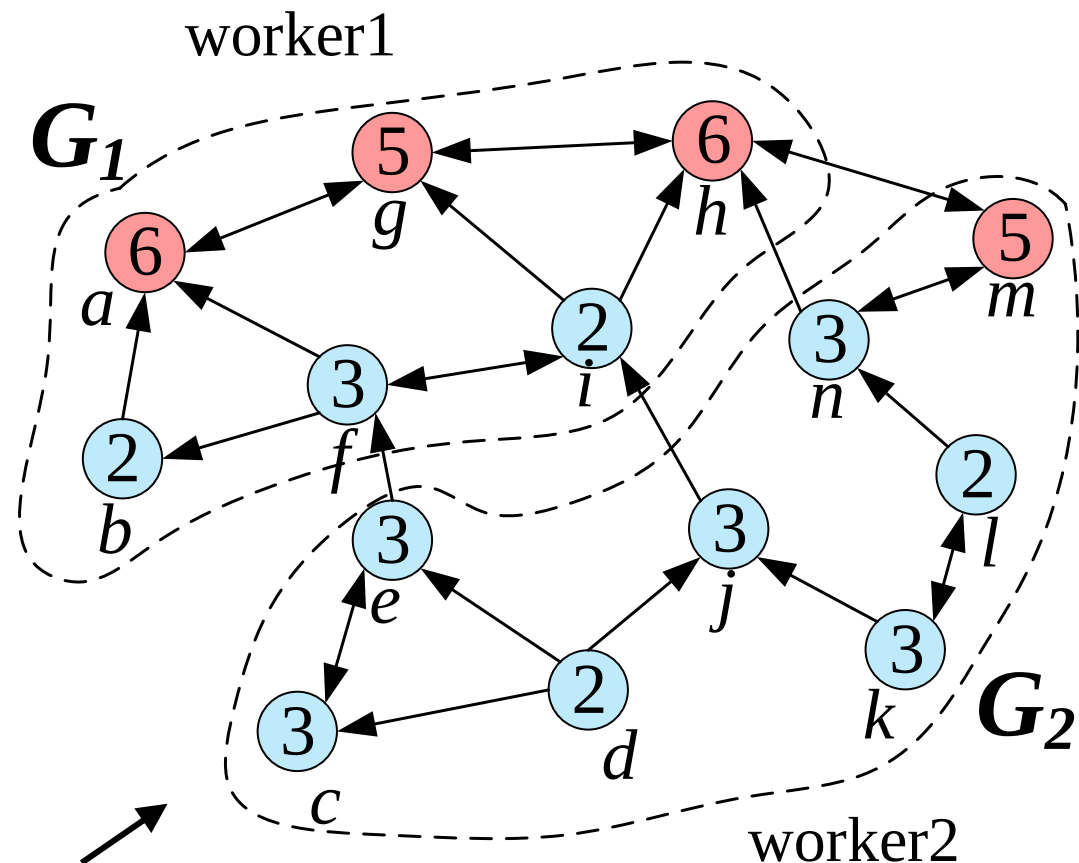


Fig. 2: hotness balance

Hotness Balanced Partition

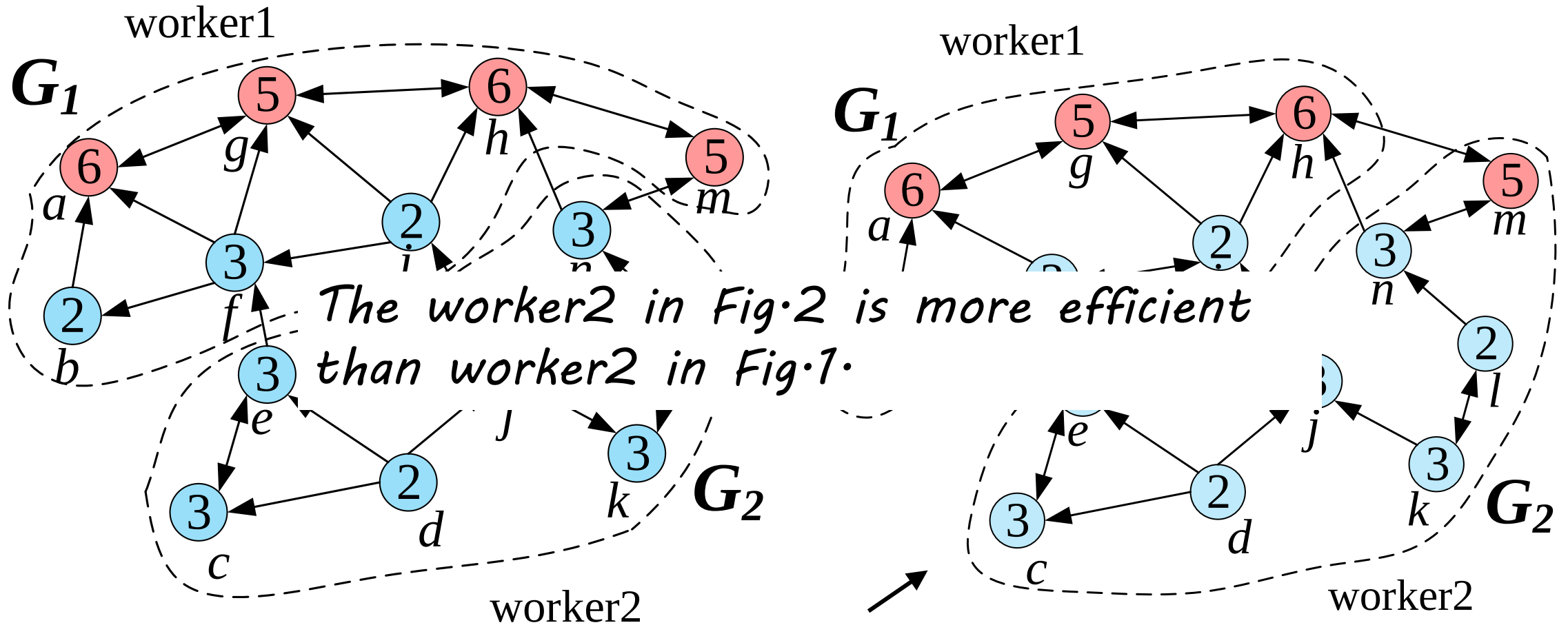


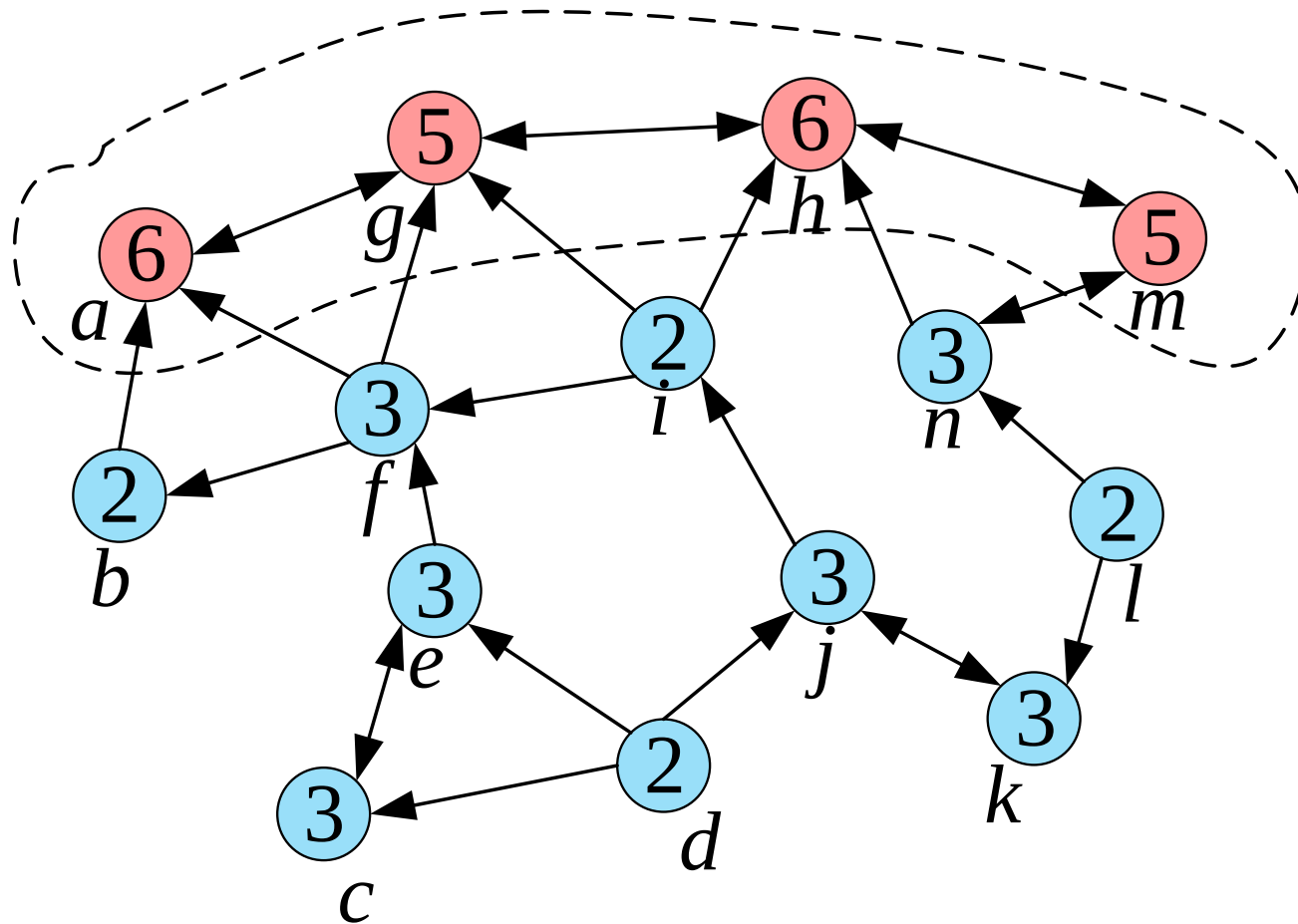
Fig. 1: vertex balance

More valid
computation

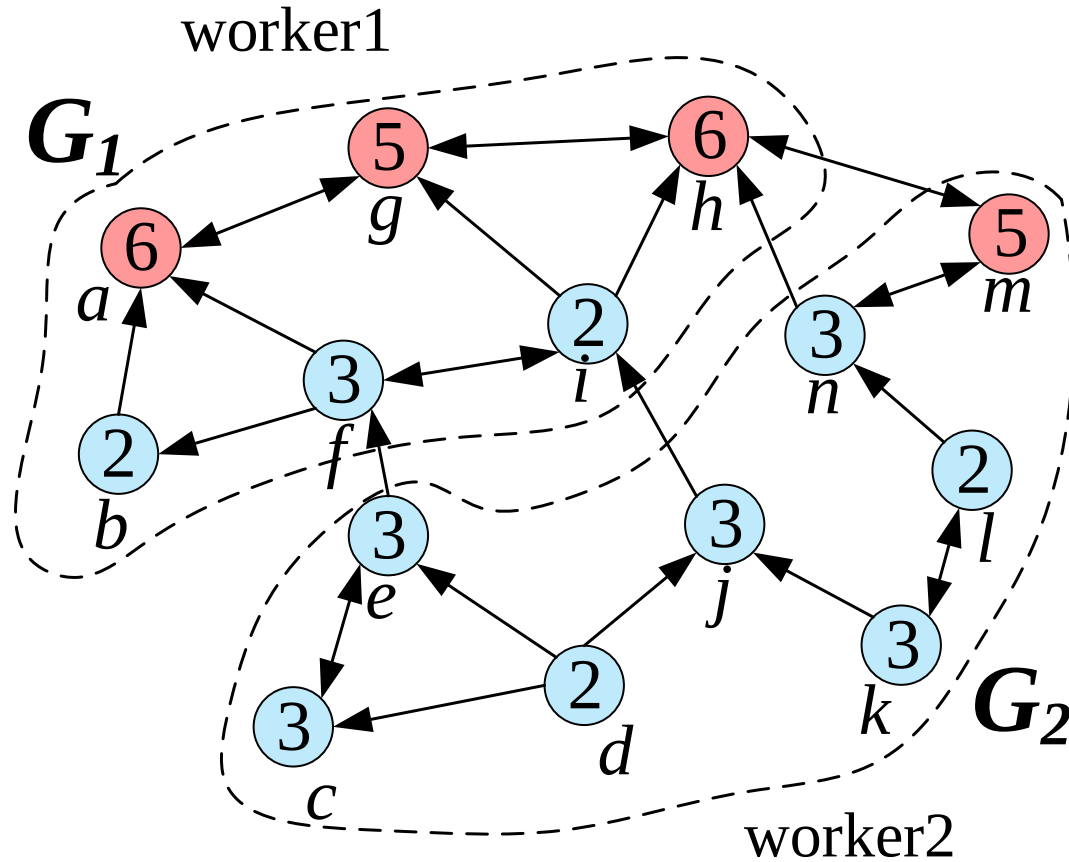
Fig. 2: hotness balance

Priority Scheduling

Accelerate graph computing by selecting hot vertices to process preferentially.

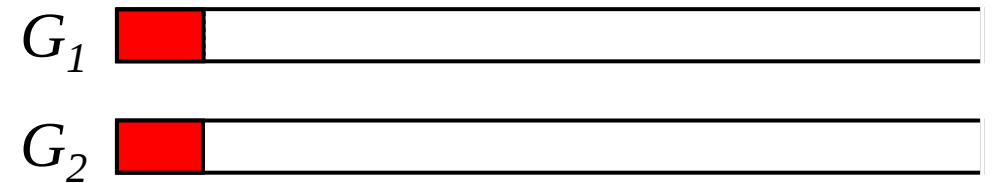


Hotness Balanced Partition



hotness balance

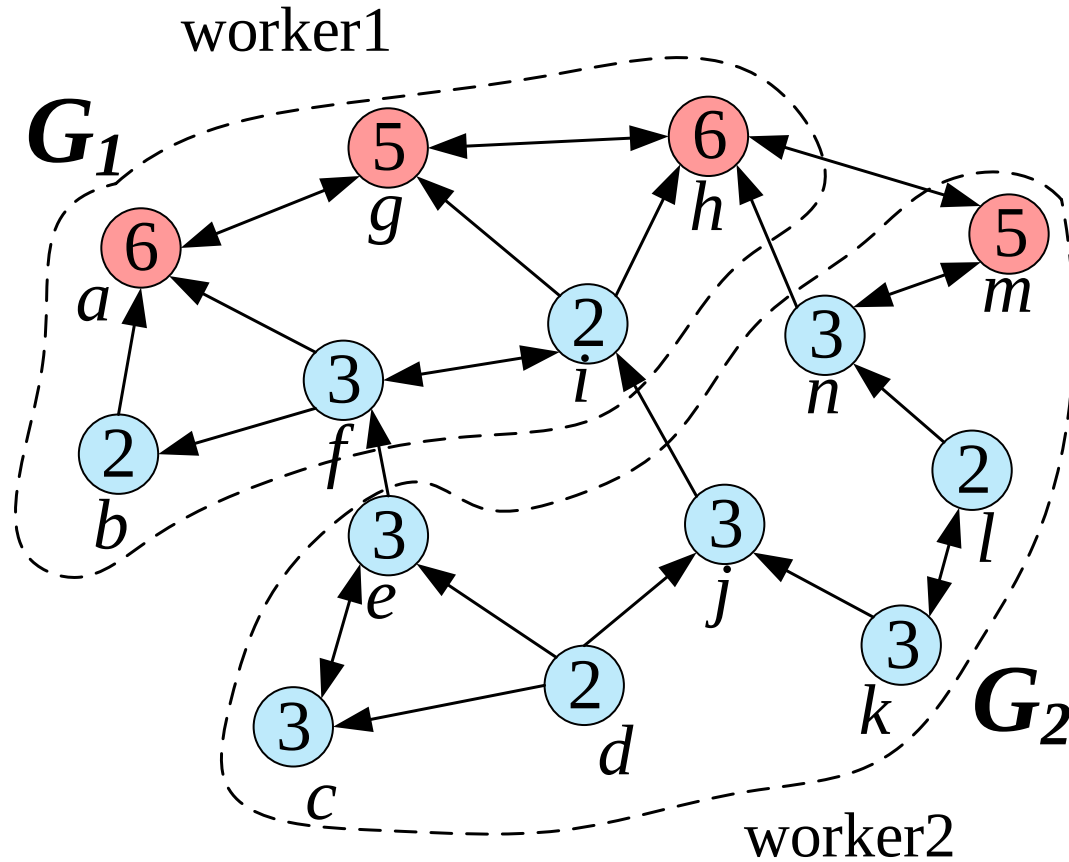
initial state $\longrightarrow$ fixed points



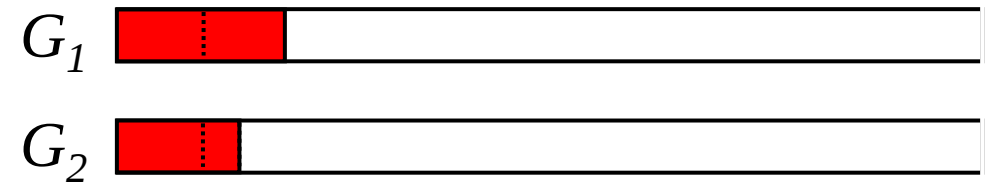
Convergence Progress Bar

Worker1 process a
Worker2 process m

Hotness Balanced Partition



initial state $\longrightarrow$ fixed points



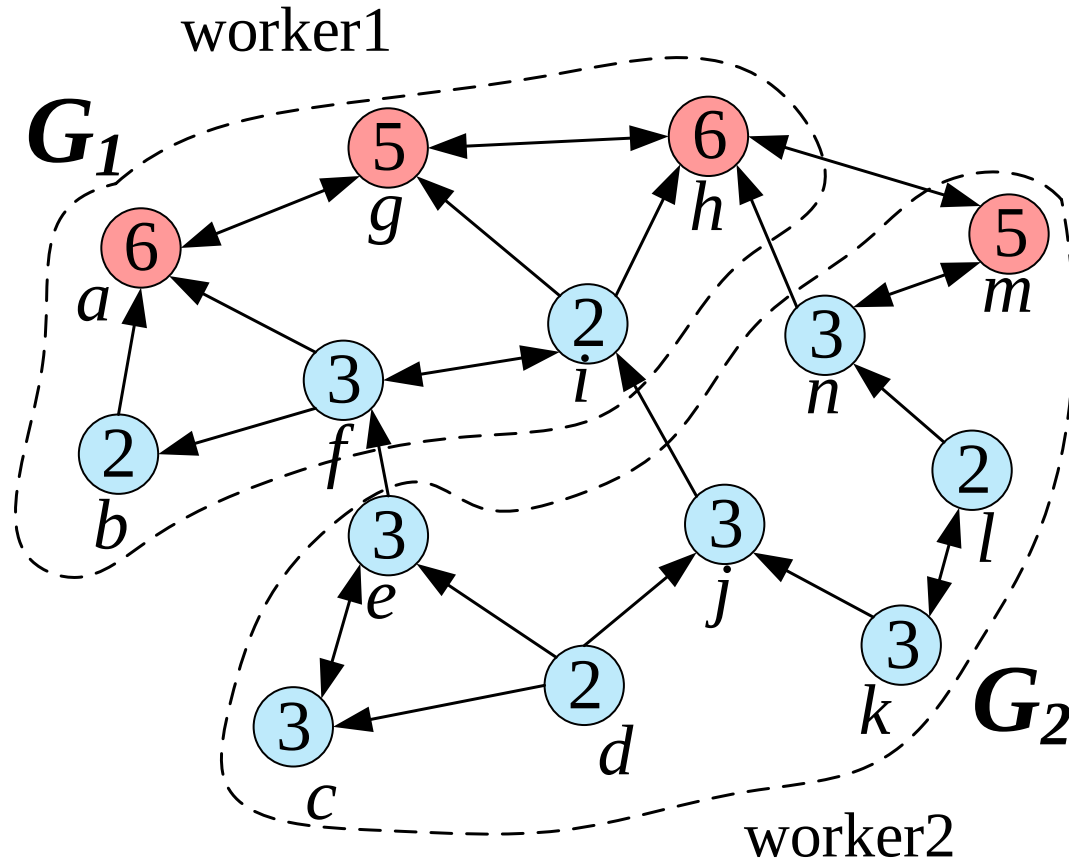
Convergence Progress Bar

Worker1 process g

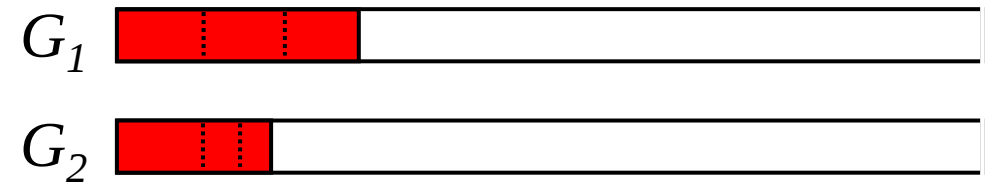
Worker2 process n

A hot vertex can make more contributions to approaching the fixed point.

Hotness Balanced Partition



initial state $\longrightarrow$ fixed points



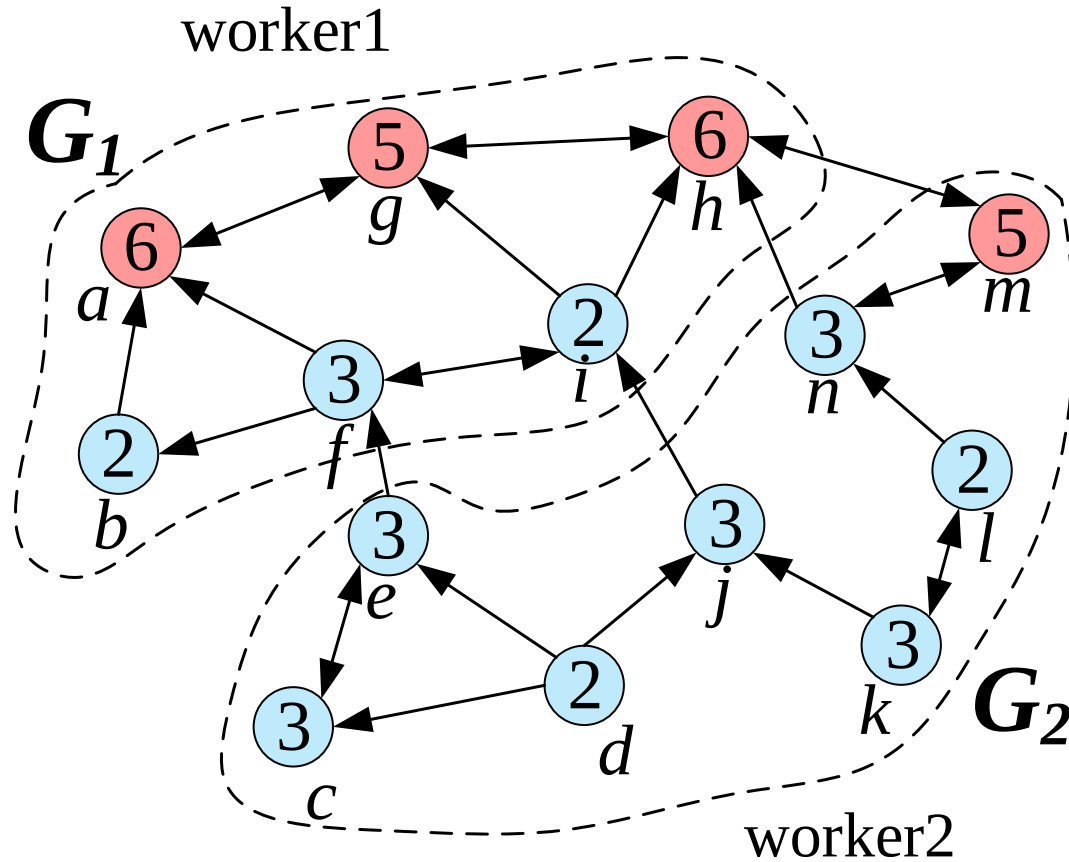
Convergence Progress Bar

Worker1 process h

Worker2 process l

A hot vertex can make more contributions to approaching the fixed point.

Hotness Balanced Partition



The worker2 is still not as efficient as we expected, because no matter how to schedule, worker2 always processes vertices with low hotness.

The hotness distribution of each partition should be the same as that of the original graph.

hotness balance

Partition Goals

prioritized iterative graph computations



- *Assign the same amount of vertex hotness to workers*
- *Minimize the variance between hotness distributions of each partition and the original graph.*
- *Minimize the communication cost between partitions.*



both synchronous and asynchronous frameworks

Partition Goals

- *Assign the same amount of vertex hotness to workers*
- *Minimize the variance between hotness distributions of each partition and the original graph.*
- *Minimize the communication cost between partitions.*

$$HJS(P||P_i) = \frac{1}{2} \left[\sum_{j=1}^z P(\mathcal{H}_j) \log \left(\frac{P(\mathcal{H}_j)}{\frac{P(\mathcal{H}_j) + P_i(\mathcal{H}_j)}{2}} \right) + \sum_{j=1}^z P_i(\mathcal{H}_j) \log \left(\frac{P_i(\mathcal{H}_j)}{\frac{P_i(\mathcal{H}_j) + P(\mathcal{H}_j)}{2}} \right) \right]$$

$$P(\mathcal{H}_j) = \frac{\sum_{v \in \mathcal{H}_j} h_v}{\sum_{v \in V} h_v}$$

HJS distance is to measure the variance between hotness distributions of each partition and the original graph.

Partition Goals

- *Assign the same amount of vertex hotness to partitions*
- *Minimize the HJS distance between each partition and the original graph.*
- *Minimize the communication cost between partitions.*

Partition Goals

- *Assign the same amount of vertex hotness to workers*
- *Minimize the HJS distance between each partition and the original graph.*
- *Minimize the communication cost between partitions.*

When balancing the hotness of each bin partition.

1. The amount of vertex hotness of each partition is equal.
2. *HJS* distance between each partition and the original graph is 0.

Partition Goals

The first two partition goals can be combined into one:

- *Balance the hotness of each bin partition.*
- *Minimize the communication cost between partitions.*

Per-Bin Hotness Balanced Partition

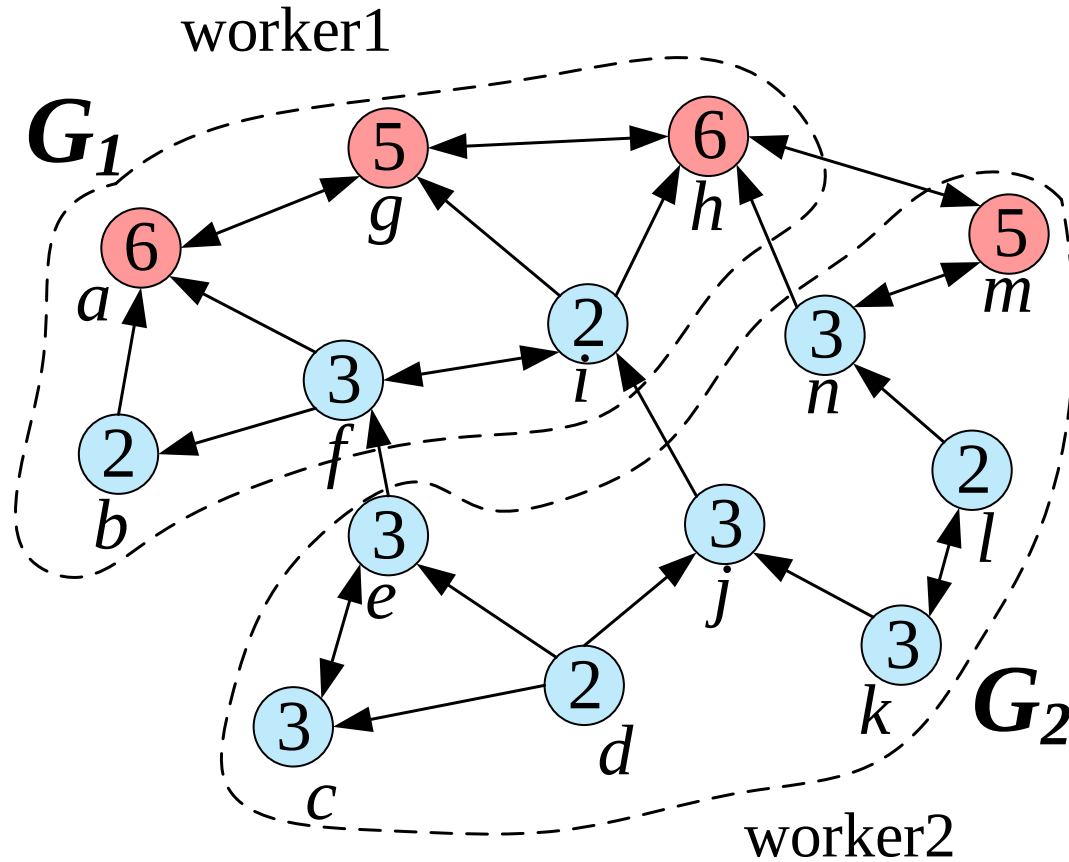


Fig. 1: hotness balance

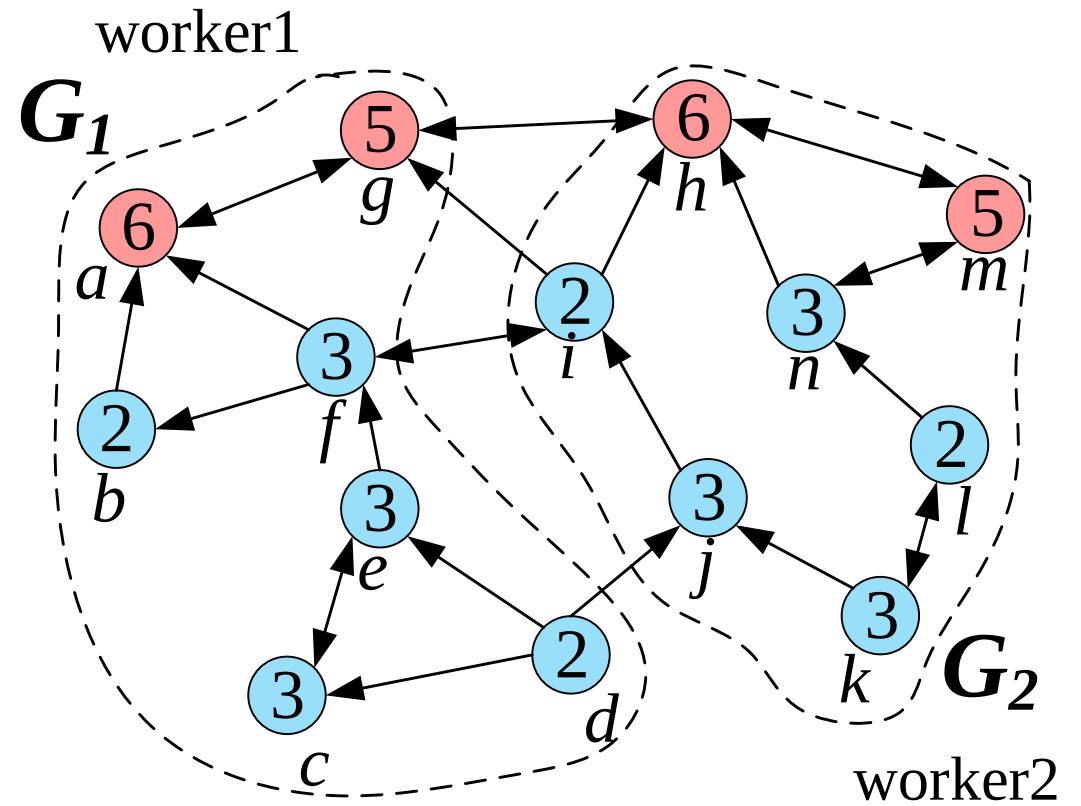
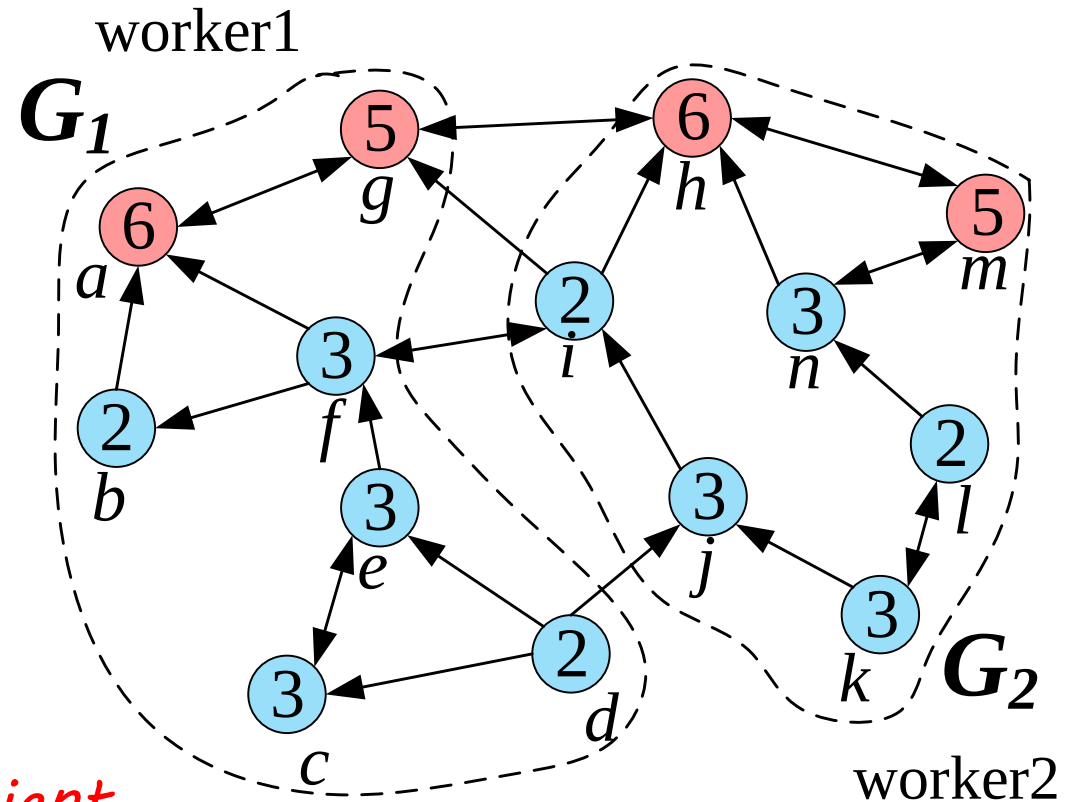


Fig. 2: per-bin hotness balance

Per-Bin Hotness Balanced Partition

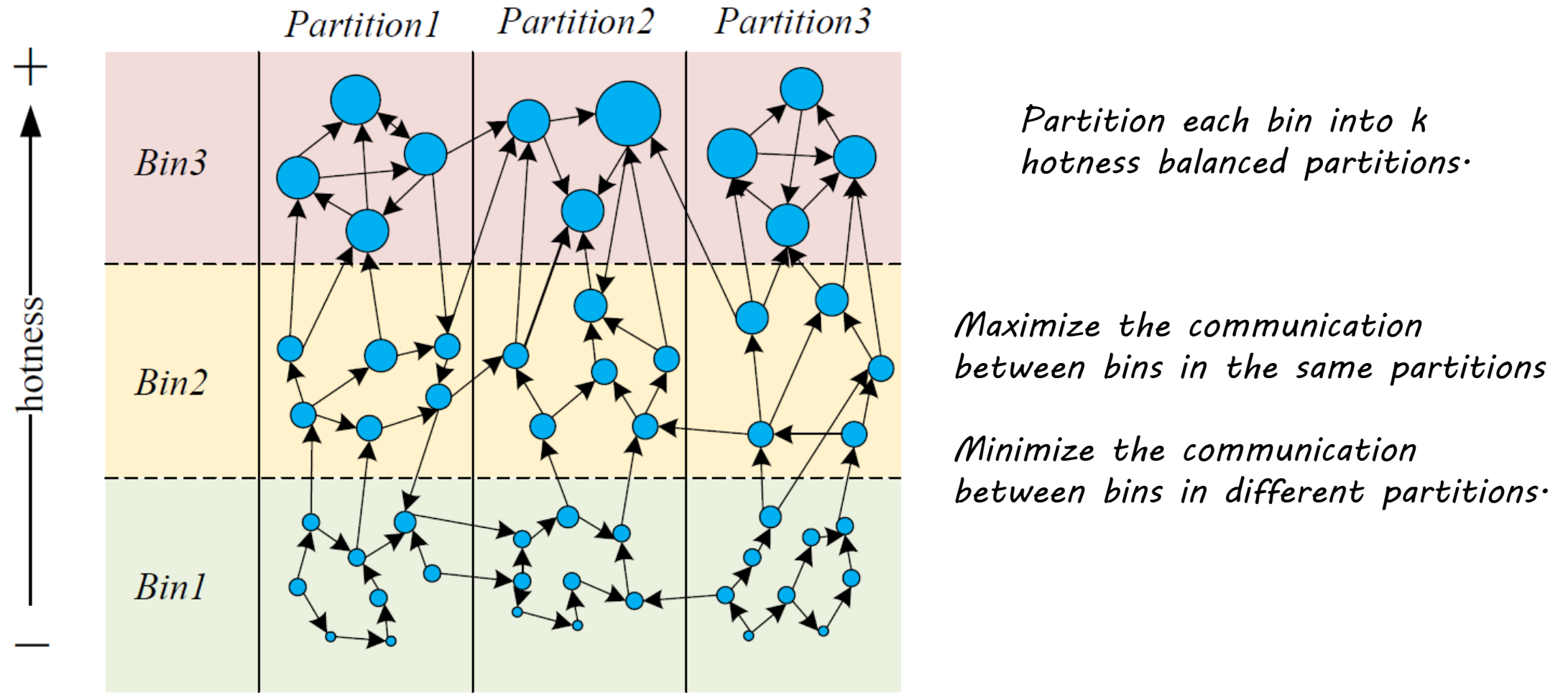
The hotness of each partition is balanced and the distribution of hotness values of each partition is the same as that of the original graph.



Both worker1 and worker2 are efficient

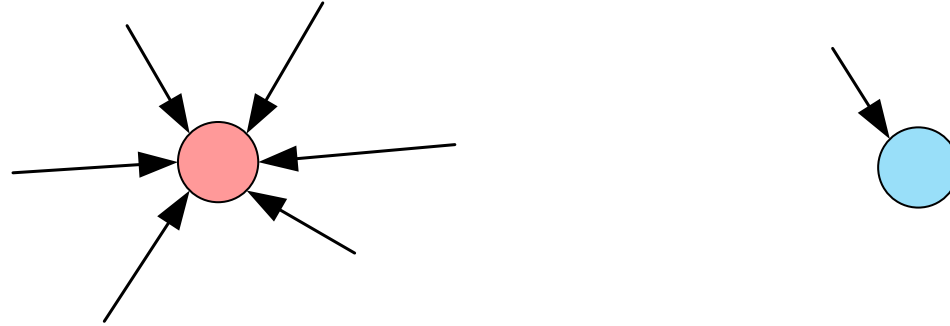
per-bin hotness balance

Per-Bin Hotness Balanced Partition



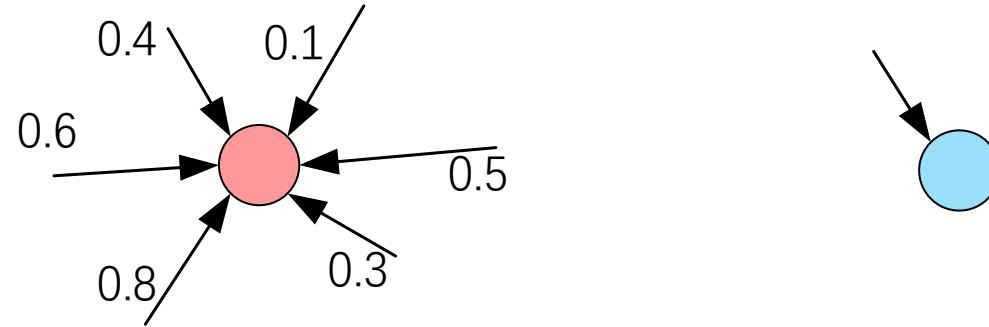
An illustration of Per-Bin hotness balanced partition

Hotness Estimation



The vertex with high indegrees always has higher execution priority and is likely to be hot.

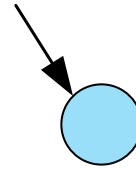
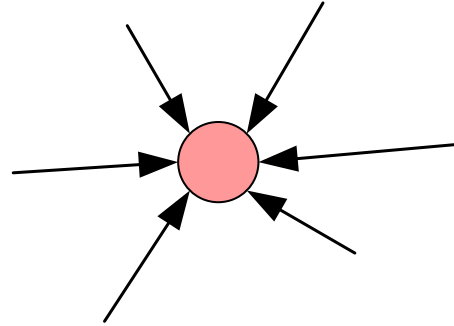
Hotness Estimation



The vertex with high indegrees always has higher execution priority and is likely to be hot.

Weights of edges may affect the hotness value of target vertices.

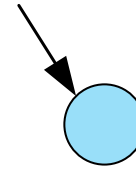
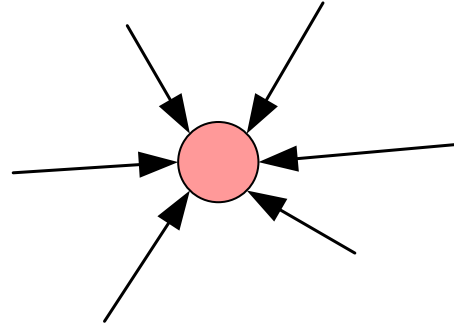
Hotness Estimation



$$h_v = \sum_{u \in IN(v)} \frac{w_{u,v}}{\sum_{w \in OUT(u)} w_{u,w}}$$

the hotness of vertex v

Hotness Estimation



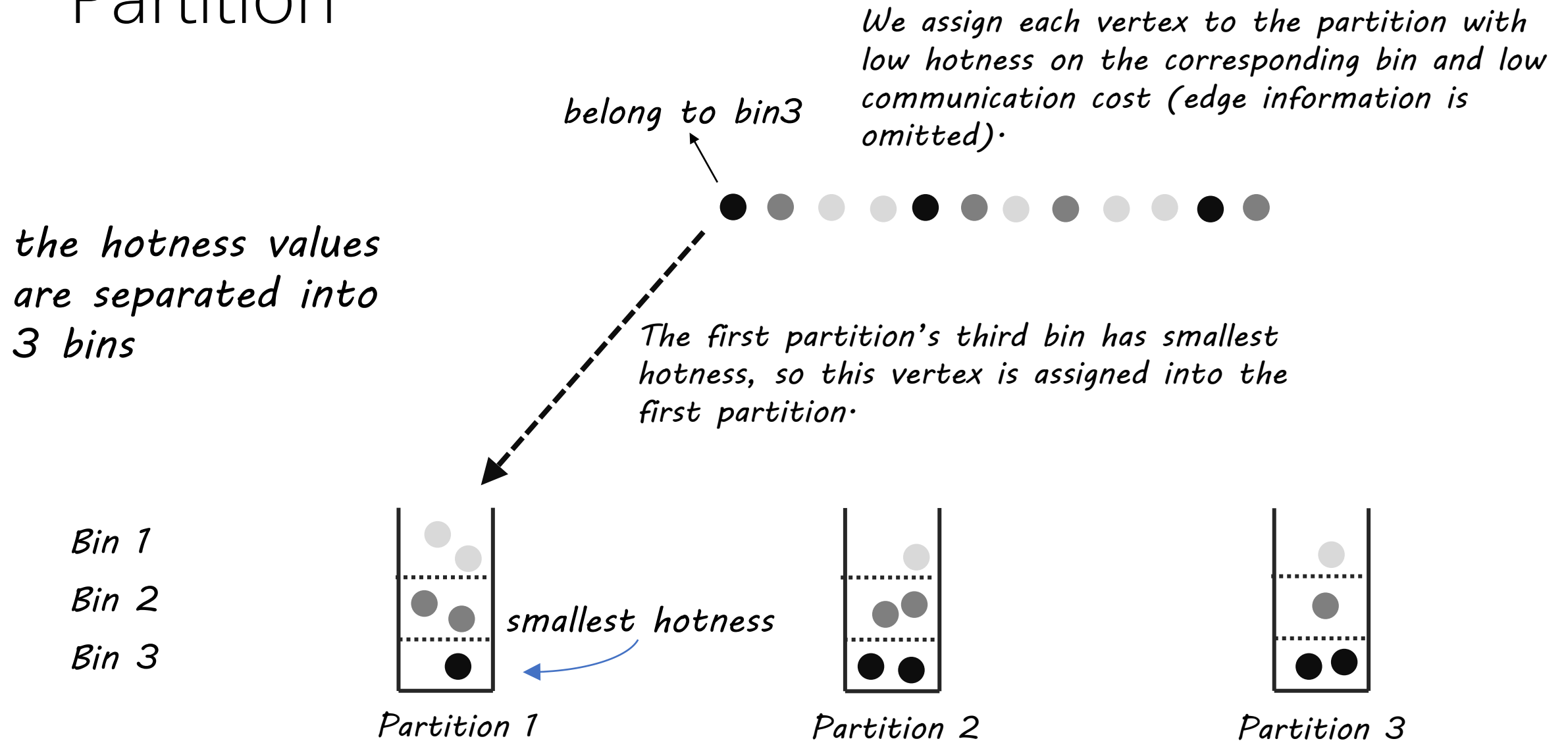
$$h_v = \sum_{u \in IN(v)} \frac{w_{u,v}}{\sum_{w \in OUT(u)} w_{u,w}}$$

the hotness of vertex v

$$com_{u,v} = h_u$$

the communication of edge $e_{u,v}$

Streamed Per-Bin Hotness Balanced Partition



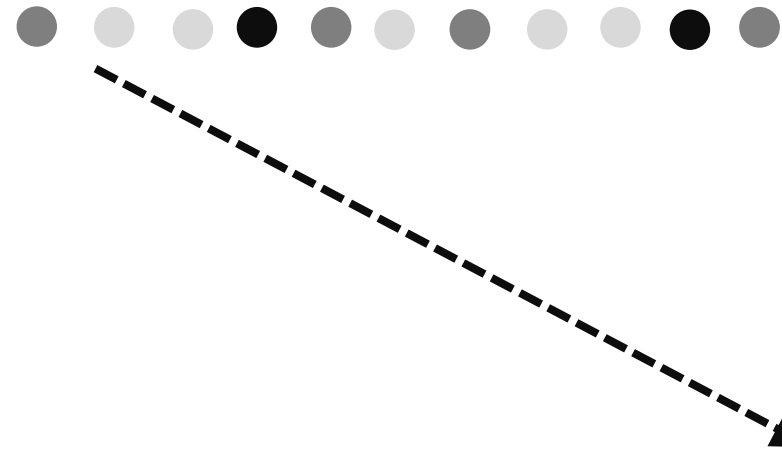
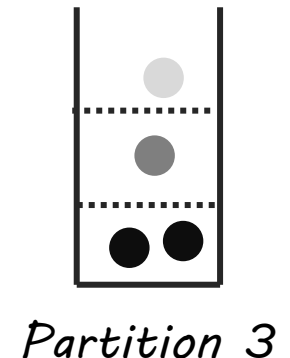
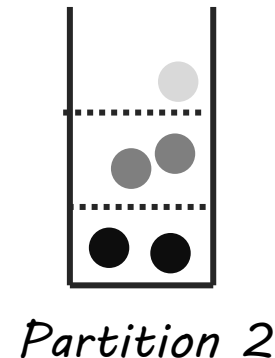
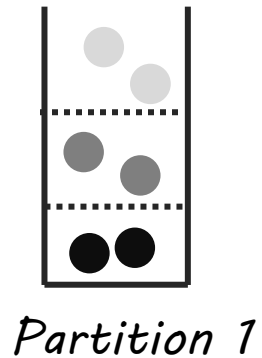
Streamed Per-Bin Hotness Balanced Partition

*the hotness values
are separated into
3 bins*

Bin 1

Bin 2

Bin 3



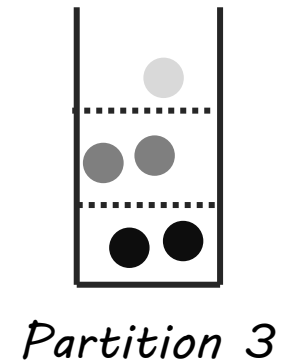
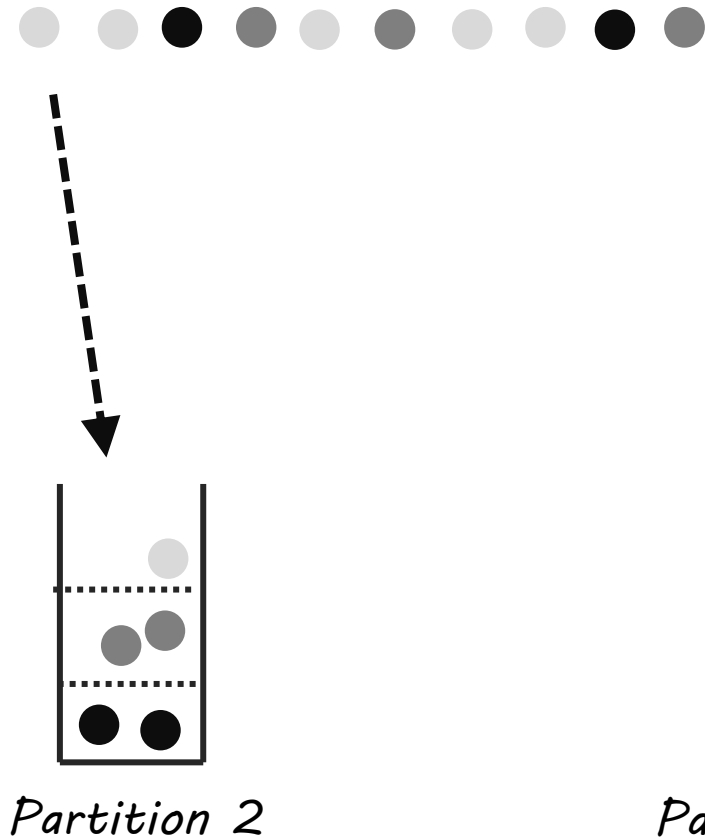
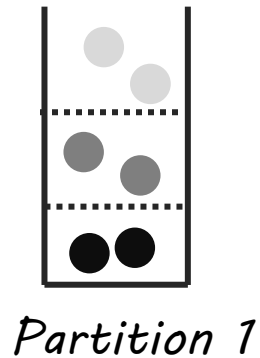
Streamed Per-Bin Hotness Balanced Partition

*the hotness values
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Bin 1

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Bin 3



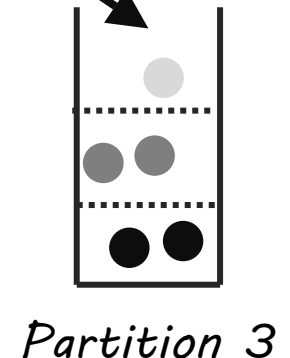
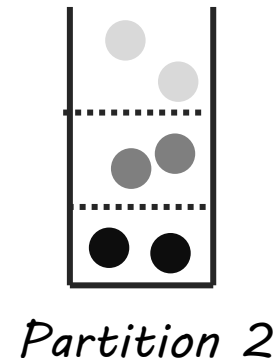
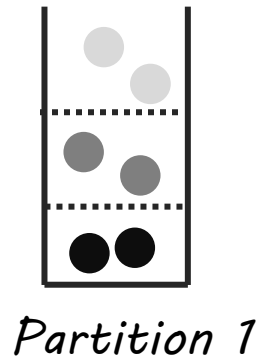
Streamed Per-Bin Hotness Balanced Partition

*the hotness values
are separated into
3 bins*

Bin 1

Bin 2

Bin 3



Streamed Per-Bin Hotness Balanced Partition

$$i = \arg \min_{i: \{\mathbf{h}_{ji} \leq \tau \frac{\sum_{v \in \mathcal{H}_j} h_v}{k}\}} \alpha \cdot ((\mathbf{h}_{ji} + h_v)^\gamma - \mathbf{h}_{ji}^\gamma) \\ + (1 - \alpha) \cdot \left(\sum_{u \notin V_i} com_{u,v} + \sum_{w \notin V_i} com_{v,w} \right)$$

where $0 \leq \alpha \leq 1$, $\tau > 1$, $\gamma > 1$, and h_{ji} is the sum of hotness values of i -th partition in the j -th bin.

Streamed Per-Bin Hotness Balanced Partition

$$i = \arg \min_{i: \{ \mathbf{h}_{ji} \leq \tau \frac{\sum_{v \in \mathcal{H}_j} h_v}{k} \}} \left(\alpha \cdot ((\mathbf{h}_{ji} + h_v)^\gamma - \mathbf{h}_{ji}^\gamma) + (1 - \alpha) \cdot \left(\sum_{u \notin V_i} com_{u,v} + \sum_{w \notin V_i} com_{v,w} \right) \right)$$

imbalance cost →

Communication cost →

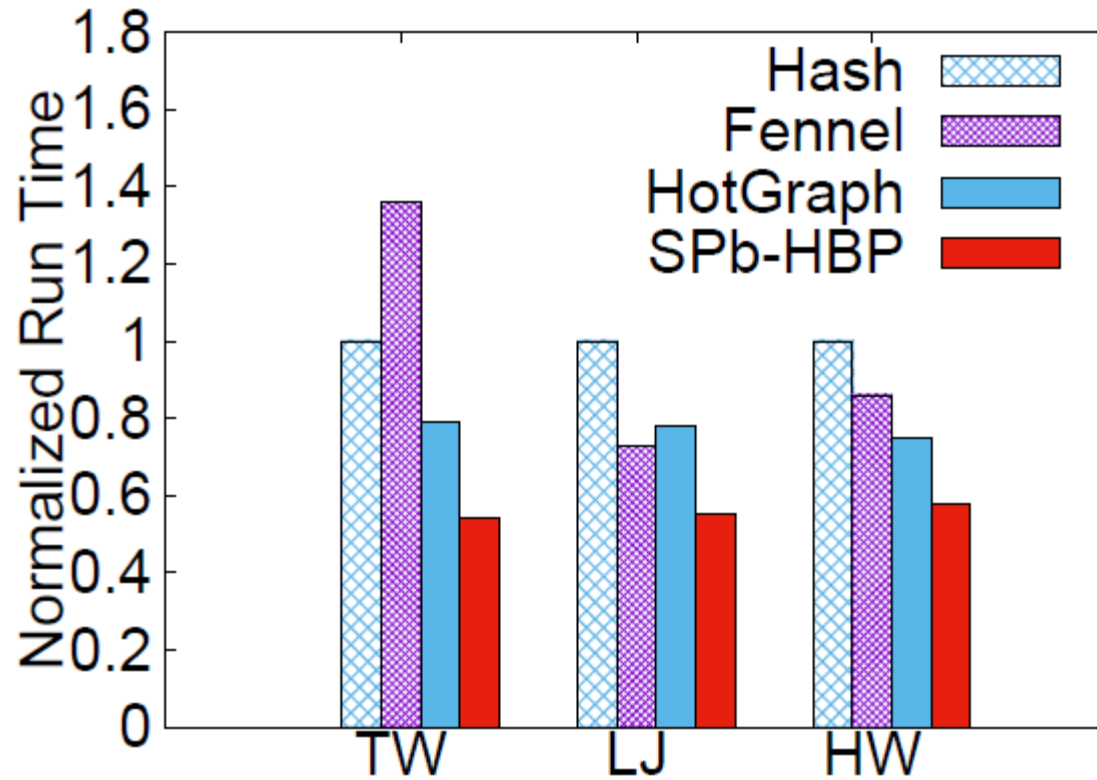
where $0 \leq \alpha \leq 1$, $\tau > 1$, $\gamma > 1$, and h_{ji} is the sum of hotness values of i -th partition in the j -th bin.

Experiment: Preparation

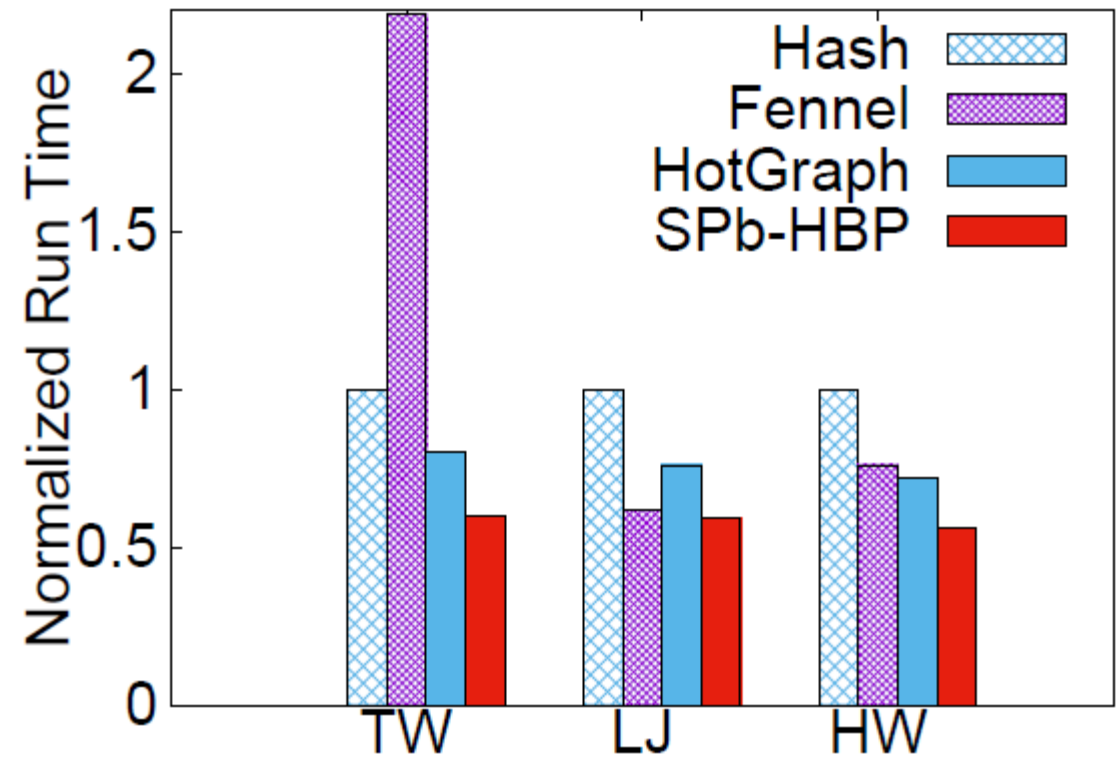
Platform	Alibaba Cloud
System	Maiter
Cluster	1 master (ecs.cs.large)
	4 slaves (ecs.cs.large)
Algorithm	PageRank, PHP
Competitors	Hash, Fennel ¹ , HotGraph ²
Data sets	Twitter (TW), LiveJournal (LJ) Hollywood (HW)

1. Tsourakakis, Charalampos, et al. "Fennel: Streaming graph partitioning for massive scale graphs." Proceedings of the WSDM 2014.
2. Zhang, Yu, et al. "HotGraph: Efficient asynchronous processing for real-world graphs." *IEEE TOC* 2016.

Experiments: Runtime Comparison



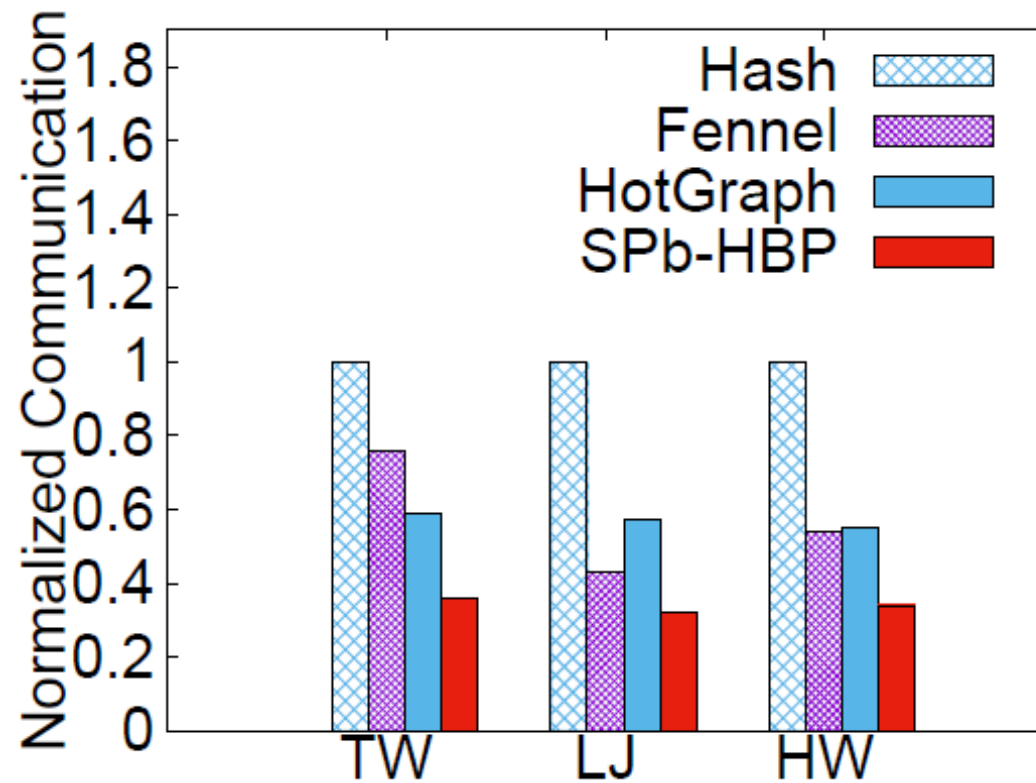
PageRank



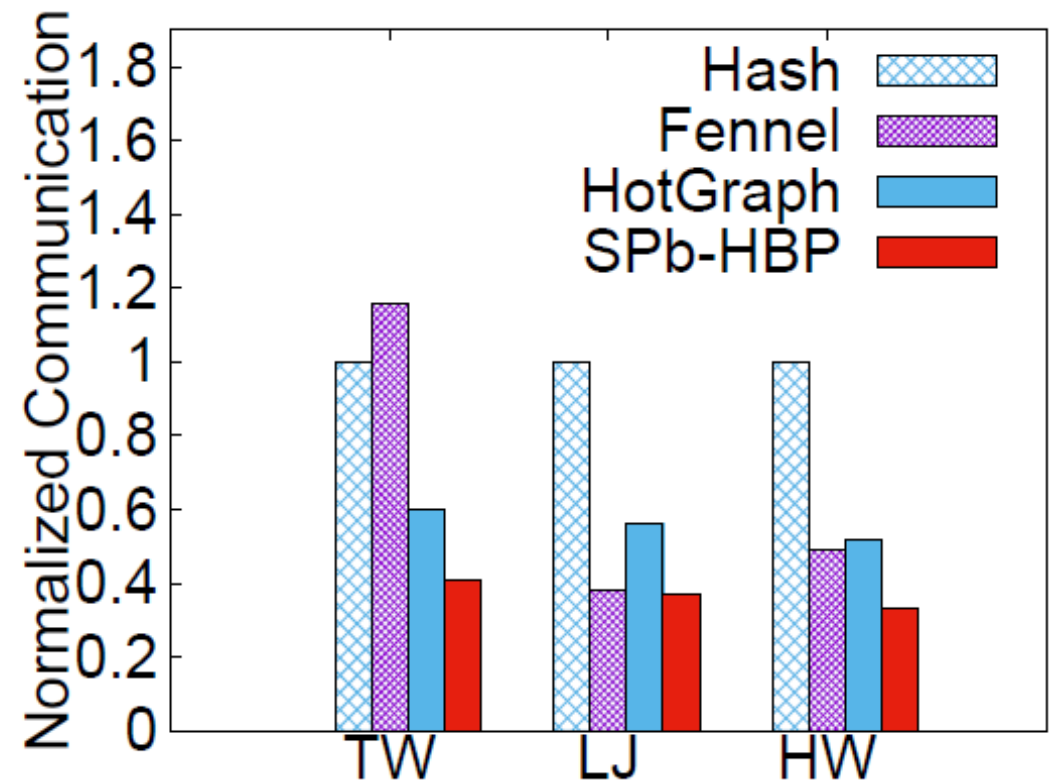
PHP

SPb-HBP is our stream-based per-bin hotness balanced partition

Experiments: Communication Cost Comparison

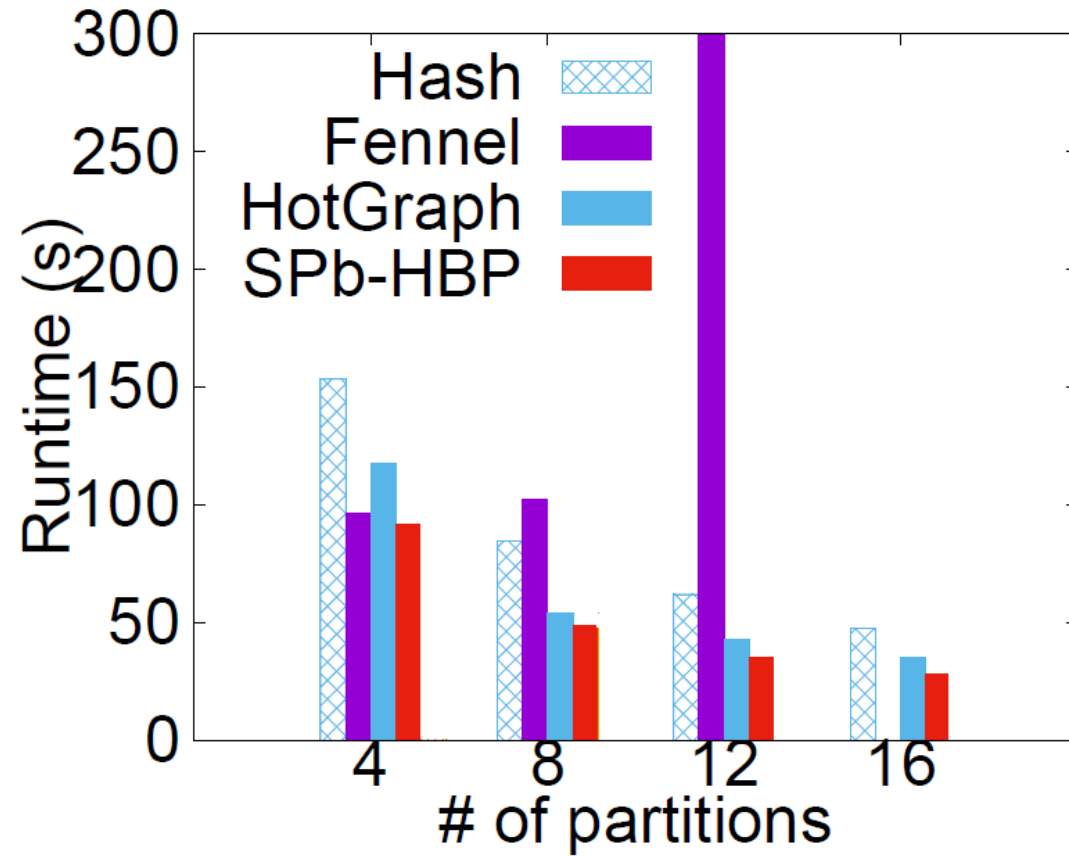


PageRank

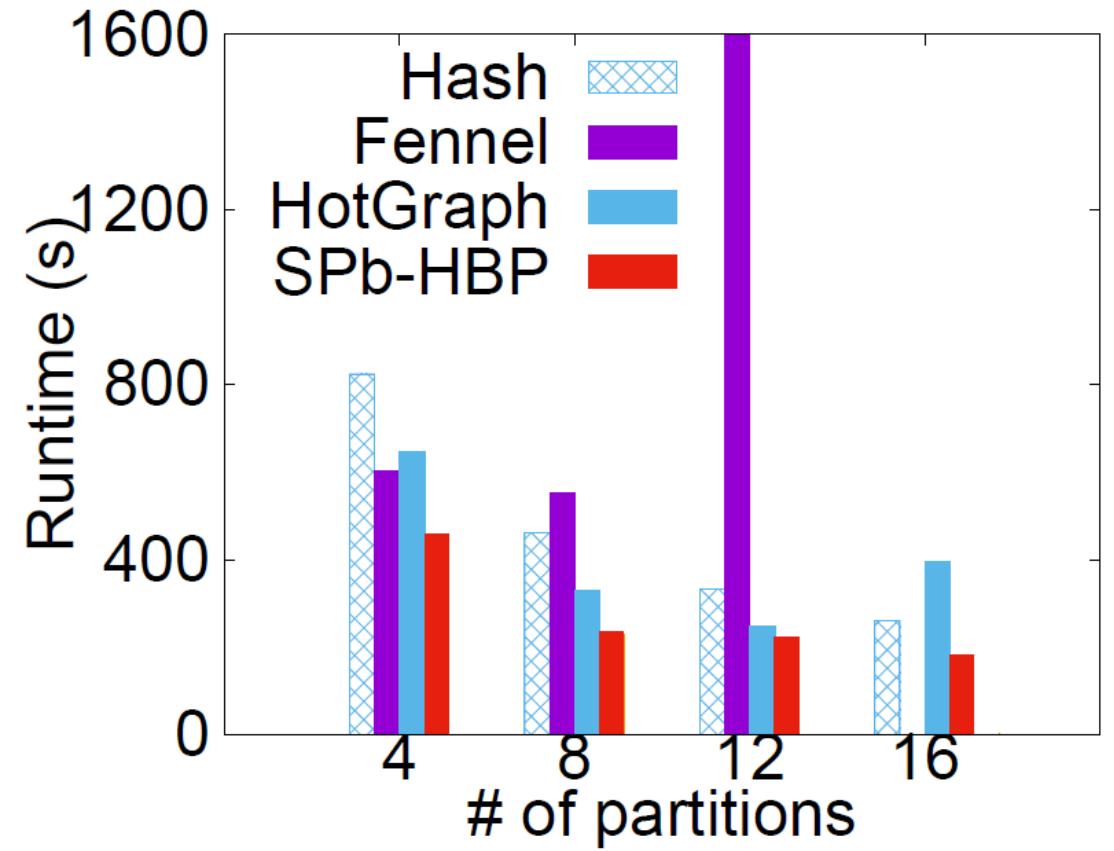


PHP

Experiments: Scalability

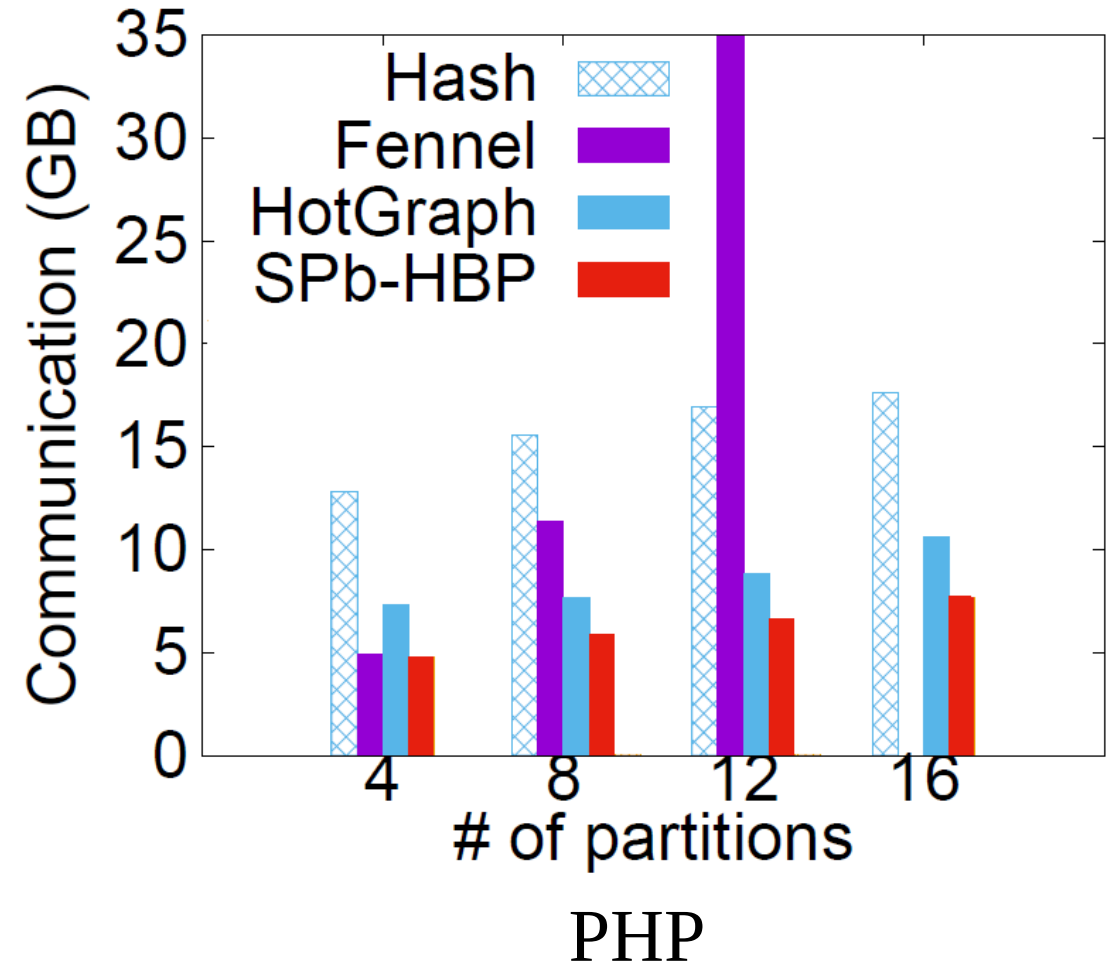
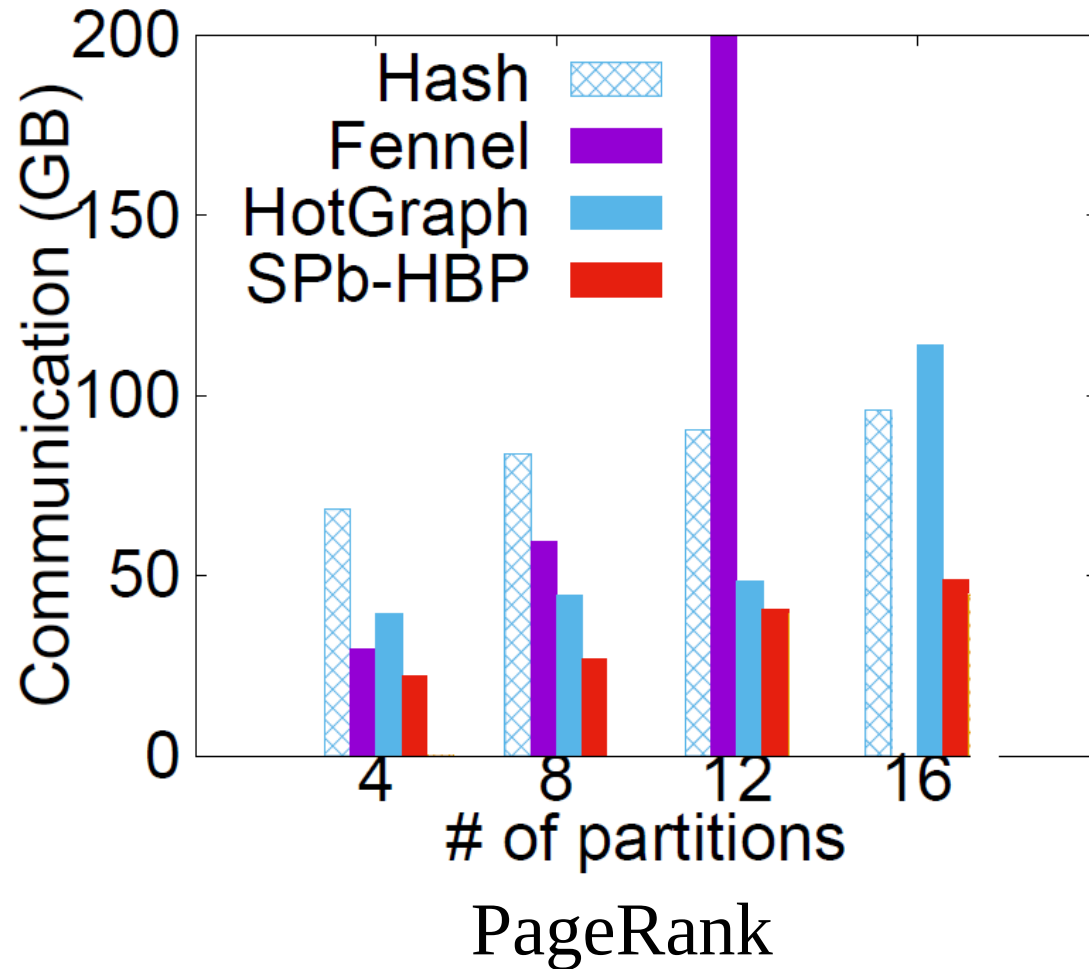


PageRank



PHP

Experiments: Scalability



Conclusion

- *The analysis of the existing graph partition methods finds that they are not suitable for asynchronous graph processing systems.*
- *A new graph partition idea, hotness balanced partition, is proposed.*
- *A stream-based per-bin hotness balanced partition algorithm is proposed.*

Thanks

*Any questions please email
gongsf@stumail.neu.edu.cn*

